B. E. MECHANICAL ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER – VII

	CONTROL ENGIN	EERING	
Course Code	18ME71	CIE Marks	40
Teaching Hours / Week (L:T:P)	3:0:0	SEE Marks	60
Credits	03	Exam Hours	03

Course Learning Objectives:

- To develop comprehensive knowledge and understanding of modern control theory, industrial automation, and systems analysis.
- To model mechanical, hydraulic, pneumatic and electrical systems.
- To represent system elements by blocks and its reduction techniques.
- To understand transient and steady state response analysis of a system.
- To carry out frequency response analysis using polar plot, Bode plot.
- To analyse a system using root locus plots.
- To study different system compensators and characteristics of linear systems.

Module-1

Introduction: Components of a control system, Open loop and closed loop systems.

Types of controllers: Proportional, Integral, Differential, Proportional-Integral, and Proportional- Integral-Differential controllers.

Modelling of Physical Systems: Mathematical Models of Mechanical, Electrical, Thermal, Hydraulic Systems. Module-2

Time domain performance of control systems: Typical test signal, Unit step response and time domain specifications of first order, second order system. Steady state error, error constants.

Module-3

Block diagram algebra, Reduction of block diagram, Signal flow graphs, Gain formula for signal flow graphs, State diagram from differential equations.

Module-4

Stability of linear control systems: Routh's criterion, Root locus, Determination of phase margin and gain margin using root locus.

Module-5

Stability analysis using Polar plot, Nyquist plot, Bode plot, Determination of phase margin and gain margin using Bode plot.

Assignment:

1.Study of On-Off Controller for Flow/ Temperature.

- 2. Study of Control Modes like P, PD, PI, PID for Pressure / Temperature / Flow.
- 3. Assignment on Root Locus, Bode Plots and Polar Plots.
- 4. Use of Software 'MATLAB' on the above topics.

Course Outcomes: At the end of the course, the student will be able to:

CO1: Identify the type of control and control actions.

- CO2: Develop the mathematical model of the physical systems.
- CO3: Estimate the response and error in response of first and second order systems subjected standard input signals.
- CO4: Represent the complex physical system using block diagram and signal flow graph and obtain transfer function.
- CO5: Analyse a linear feedback control system for stability using Hurwitz criterion, Routh's criterion and root Locus technique in complex domain.

CO6: Analyse the stability of linear feedback control systems in frequency domain using polar plots, Nyquist and Bode plots.

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.
- There will be two full questions (with a maximum of four sub- questions) from each module.
- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.

SI. No.	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year
Textbo	ok/s			
1	Automatic Control Systems	Farid G., Kuo B. C	McGraw Hill Education	10th Edition,2018
2	Control systems	Manik D. N	Cengage	2017
Refere	nce Books			L
1	Modern control Engineering	K. Ogeta	Pearson	5th Edition, 2010
2	Control Systems Engineering	Norman S Nice		Fourth Edition, 2007
3	Modern control Systems	Richard C Dorf		
4	Control Systems Engineering	ljNagrath, M Gopal	New Age International (P) Ltd	
5	Control Systems Engineering	S Palani	Tata McGraw Hill Publishing Co Ltd	ISBN-13 9780070671

	SEMESTER - VI		
	PUTER AIDED DESIGN AND		
Course Code	18ME72	CIE Marks	40
Teaching Hours /Week (L:T:P)	3:0:0	SEE Marks	60
Credits Course Learning Objectives:	03	Exam Hours	03
 To impart knowledge of C mathematical models. To make students to under 	erstand the Computer Applic r integrated systems. Enable	erent concepts of automation b ations in Design and Manufactu them to perform various trans	uring [CAD /
 Manufacturing Systems. To expose students to complanning etc. To expose the students to 	nputer aided process plannii CNC Machine Tools, CNC pa	r lines, Line Balancing Techniqu ng, material requirement plann Irt programming, and industrial nufacturing, Internet of Things,	ing, capacity I robots.
4.0 leading to Smart Facto	ory.		
Module-1			
problems. Automated Production Lines and			
automated flow lines, buffer stora lines without storage, partial auto fundamentals of automated assen	ge, control of production lin mation, analysis of automat	e, analysis of transfer lines, and	alysis of flow
	ge, control of production lin mation, analysis of automat	e, analysis of transfer lines, and	alysis of flow
lines without storage, partial auto fundamentals of automated assen Module-2 CAD and Computer Graphics Sof configuration, functions of graphic Transformations: 2D transformatic concatenation, numerical problem Computerized Manufacture Plan	ge, control of production lin mation, analysis of automation hbly systems, numericals. tware: The design process, cs package, constructing the ons, translation, rotation and ns on transformations. hing and Control System: Co	e, analysis of transfer lines, and ed flow lines with storage buffe applications of computers in o geometry. d scaling, homogeneous transfo	alysis of flow er, design, softwar ormation matri ng, Retrieval an
lines without storage, partial auto fundamentals of automated assen Module-2 CAD and Computer Graphics Sof configuration, functions of graphic Transformations: 2D transformatic concatenation, numerical problem Computerized Manufacture Plant Generative Systems, benefits of System, computer integrated pro MRP system, working of MRP, of Shon floor control	ge, control of production lin mation, analysis of automation holy systems, numericals. tware: The design process, cs package, constructing the ons, translation, rotation and ns on transformations. hing and Control System: Co CAPP, Production Planning oduction management system	e, analysis of transfer lines, and ed flow lines with storage buffe applications of computers in o geometry. d scaling, homogeneous transfo omputer Aided Process Plannir and Control Systems, typical a em, Material Requirement Plan	alysis of flow er, design, softwar prmation matrix ng, Retrieval an activities of PP nning, inputs t
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lines without storage, partial auto fundamentals of automated assen Module-2 CAD and Computer Graphics Sof configuration, functions of graphic Transformations: 2D transformatic concatenation, numerical problem Computerized Manufacture Plann Generative Systems, benefits of System, computer integrated pro MRP system, working of MRP, of Shon floor control Module-3 Flexible Manufacturing Systems:	ge, control of production lin mation, analysis of automation holy systems, numericals. tware: The design process, cs package, constructing the ons, translation, rotation and ns on transformations. hing and Control System: Co CAPP, Production Planning oduction management system utputs and benefits, Capaci Fundamentals of Group Te	e, analysis of transfer lines, and ed flow lines with storage buffe applications of computers in o geometry. d scaling, homogeneous transfo omputer Aided Process Plannir and Control Systems, typical a em, Material Requirement Plan ty Planning, Computer Aided chnology and Flexible Manufac	alysis of flow er, design, softwar ormation matri ng, Retrieval an activities of PP nning, inputs t Quality Contro cturing System
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lines without storage, partial auto fundamentals of automated assen Module-2 CAD and Computer Graphics Sof configuration, functions of graphic Transformations: 2D transformatic concatenation, numerical problem Computerized Manufacture Plann Generative Systems, benefits of the System, computer integrated proc MRP system, working of MRP, of Shon floor control Module-3 Flexible Manufacturing Systems: types of FMS, FMS components, control systems, FMS planning a	ige, control of production lin mation, analysis of automation inbly systems, numericals. tware: The design process, cs package, constructing the ons, translation, rotation and is on transformations. ning and Control System: Con CAPP, Production Planning oduction management system utputs and benefits, Capaci Fundamentals of Group Te Material handling and stor nd design issues, Automate	e, analysis of transfer lines, and ed flow lines with storage buffe applications of computers in o geometry. d scaling, homogeneous transfo omputer Aided Process Plannir and Control Systems, typical a em, Material Requirement Plan ty Planning, Computer Aided chnology and Flexible Manufac rage system, applications, ber	alysis of flow er, design, softwar ormation matri ng, Retrieval an activities of PP nning, inputs t Quality Contro cturing System nefits, compute
lines without storage, partial auto fundamentals of automated assen Module-2 CAD and Computer Graphics Sof configuration, functions of graphic Transformations: 2D transformatic concatenation, numerical problem Computerized Manufacture Plane Generative Systems, benefits of System, computer integrated pro MRP system, working of MRP, of Shon floor control Module-3 Flexible Manufacturing Systems: types of FMS, FMS components,	ige, control of production lin mation, analysis of automation inbly systems, numericals. tware: The design process, cs package, constructing the ons, translation, rotation and is on transformations. ning and Control System: Control Syst	e, analysis of transfer lines, and ed flow lines with storage buffe applications of computers in o geometry. d scaling, homogeneous transfo omputer Aided Process Plannir and Control Systems, typical a em, Material Requirement Plan ty Planning, Computer Aided chnology and Flexible Manufac rage system, applications, ber ed Storage and Retrieval Syste	alysis of flow er, design, softwar ormation matri ng, Retrieval ar activities of PF nning, inputs to Quality Contro cturing System nefits, compute ems, AS/RS ar

balancing, computerized line balancing methods.

Module-4

Computer Numerical Control: Introduction, components of CNC, CNC programming, manual part programming, G Codes, M Codes, programming of simple components in turning, drilling and milling systems, programming with canned cycles. Cutter radius compensations.

Robot Technology: Robot anatomy, joints and links, common robot configurations, robot control systems, accuracy and repeatability, end effectors, sensors in robotics. Robot programming methods: on-line and off-line methods. Robot industrial applications: material handling, processing and assembly and inspection.

Module-5

Additive Manufacturing Systems: Basic principles of additive manufacturing, slicing CAD models for AM, advantages and limitations of AM technologies, Additive manufacturing processes: Photo polymerization, material jetting, binder jetting, material extrusion, Powder bed sintering techniques, sheet lamination, direct energy deposition techniques, applications of AM.

Future of Automated Factory: Industry 4.0, functions, applications and benefits. Components of Industry 4.0, Internet of Things (IOT), IOT applications in manufacturing, Big-Data and Cloud Computing for IOT, IOT for smart manufacturing, influence of IOT on predictive maintenance, industrial automation, supply chain optimization, supply-chain & logistics, cyber-physical manufacturing systems.

Course Outcomes: At the end of the course, the student will be able to:

CO1: Define Automation, CIM, CAD, CAM and explain the differences between these concepts. Solve simple problems of transformations of entities on computer screen

CO2: Explain the basics of automated manufacturing industries through mathematical models and analyze different types of automated flow lines.

CO3: Analyse the automated flow linestoreduce time and enhance productivity.

CO4: Explain the use of different computer applications in manufacturing, and able to prepare part programs

forsimple jobs on CNC machine tools and robot programming.

CO5: Visualize and appreciate the modern trends in Manufacturing like additive manufacturing, Industry 4.0 and applications of Internet of Things leading to Smart Manufacturing.

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.
- There will be two full questions (with a maximum of four sub- questions) from each module.
- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.

SI No	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year	
Textbo	ok/s				
1	Automation, Production Systems and Computer-Integrated Manufacturing	Mikell P Groover	Pearson Learning.	4 th Edition,2015	
2	CAD / CAM Principles and Applications	P N Rao	Tata McGraw-Hill	3 rd Edition, 2015	
3	CAD/CAM/CIM	Dr. P. Radhakrishnan	New Age International Publishers, New Delhi.	3 rd edition	
Referer	nce Books				
1	"CAD/CAM"	Ibrahim Zeid	Tata McGraw Hill.		
2	Principles of Computer Integrated Manufacturing	S.Kant Vajpayee	, Prentice Hall of India, New Delhi.	1999	

	Work Systems And The Methods,	Current M4		Upper Saddle
3	Measurement And Management of	Groover M. PPearson	Prentice Hall	River, NJ,
	Work	r.,rearson		2007.
4	Computer Automation in	Boucher, T. O.,	London, UK,	1996.
4	Manufacturing	Chapman & Hall		
5	Introduction to Robotics:	Craig, J. J.	Addison-Wesley	2 nd Ed 1989.
5	Mechanics And Control		Publishing Company	2 20 20001
	Internet of Things (IoT): Digitize or			
6	Die: Transform your organization.	Nicolas	Amazon.	
	Embrace the digital evolution. Rise	Windpassinger		
	above the competition			
7	Internet of Things: A Hands-on	ArshdeepBahga	Universities Press	
7	Approach"	and Vijay Madisetti		
	Additive Manufacturing	lan Gibson,		
8	Technologies: Rapid Prototyping to	David W. Rosen,		2nd Ed. (2015)
0	Direct Digital Manufacturing,	Brent Stucker		
	Understanding Additive	Andreas		
9	Manufacturing	Gebhardt,		2011
9		Hanser		
		Publishers		
	Understanding Additive	Andreas		
10	Manufacturing",	Gebhardt,	Hanser Publishers,	2011
		Geonarut,		

Choice Based Cr	B. E. MECHANICAL ENGI edit System (CBCS) and Outo	NEERING come Based Education (OBE)	
	SEMESTER – VII		
	Professional Electiv	ve 2	
	DESIGN FOR MANUFA	CTURE	
Course Code	18ME731	CIE Marks	40
Teaching Hours / Week (L:T:P)	3:0:0	SEE Marks	60
Credits	03	Exam Hours	03
Course Learning Objectives:			
	tors to be considered in desig	gning parts and components w	ith focus on
manufacturability.			
		netric tolerances and true posi	tion tolerance
techniques in manufacture			
 To impart the knowledge or 	n design considerations for d	esigning components produce	d using various
machining operations like t	urning, drilling, milling, grind	ing etc.	
 To educate the students or 	design rules and recommen	dations for processes like casti	ng, welding,
forgings powder metallurg	and injection moulding.		
Module-1			
Introduction: Definition, need for	DFM, DFM approach for cos	t reduction, general design gu	ide lines of DFN
advantages and disadvantages, ap	olication of DFM in industrie	es, Design for Quality Manufac	turability, DFQN
approach, designing for economica	l production. Design for Exce	llence (DFX).	
Engineering Tolerancing: Basics of	of dimensional tolerancing,	Redundancy, tolerance allocation	ation, Review o
relationship between attainable to	erance grades and different	machining processes. Geometr	rical tolerances.
Process capability, mean, variance	, skewness, kurtosis, proces	is capability indices- C_p , and (C _{pk} . Cumulativ
effect of tolerance- Sure fit law and	truncated normal law, prob	lems.	
Module-2			
True positional theory: Comparis	on between coordinate and	true position method of featu	re location. Tru
position tolerance- virtual size con	cept, concepts of datum and	d changing datum, floating and	d fixed fasteners
projected tolerance zone and func			
true position tolerancing.			· ·
Selective Assembly: Interchangeab	le part manufacture and sele	ective assembly. Deciding the n	umber of group
-model-1: group tolerance of matir			
of axial play- introducing secondary			·
Module-3	<u> </u>	-/ - F 50.	
Datum Features: Functional datum	datum for manufacturing of	hanging the datum examples	

Component Design:Design features to facilitate machining: drills, milling cutters, keyways, Doweling procedures, counter sunk screws, Reduction of machined area, simplification by separation, simplification by amalgamation, Design for machinability, Design for economy, Design for clampability, Design for accessibility. Designing for heat treatment, roller burnishing, and economical de-burring.

Module-4

Design of components with casting considerations: Pattern, mould, and parting line. Cored holes and machined holes. Identifying the possible and probable parting lines. Castings requiring special sand cores. Designing to obviate sand cores.

Welding considerations: Advantages of weldments over other design concepts, design requirements and rules, redesign of components for welding; case studies.

Engineering Design for

Design for Economical

Processes and Materials of

Manufacture

Production

Manufacture

3

4

5

Modu	le-5			
Forgin	g considerations -requirements a	nd rules-redesign of	f components for forging and case	e studies.
Desigr	n of components for powder meta	allurgy - requiremen	ts and rules-case studies.	
Desigr	n of components for injection mo	ulding- requirement	ts and rules-case studies.	
Course	e Outcomes: At the end of the cou	urse, the student wi	ll be able to:	
CO1: S	Select proper materials and manuf	facturing processes	for designing products/componer	nts by applying th
re	elevant principles for ease and ec	onomic production.		
CO2: I	dentify faulty design factors leading	ng to increased cost	s in producing mechanical compo	nents.
CO3: A	Apply appropriate design tolerance	es – dimensional, ge	ometric and true position toleran	ices for the
р	roduction processes of mechanic	al components.		
CO4: A	Apply the concepts related to redu	icing machined area	s, simplification by amalgamation	and separation,
С	lampability, accessibility etc., in th	ne design of mechan	ical components.	
CO5: A	Analyse the design of castings, wel	ldments, forgings, p	owder metallurgy components an	id suggest design
n	nodifications to reduce the cost.			
Quest	ion paper pattern:			
•	The question paper will have ten f	full questions carryin	ng equal marks.	
•				
	Each full question will be for 20 m	arks.		
	Each full question will be for 20 m There will be two full questions (w		our sub- questions) from each mo	odule.
•	There will be two full questions (w	vith a maximum of f	, ,	odule.
•	•	vith a maximum of f uestion covering all	the topics under a module.	
•	There will be two full questions (w Each full question will have sub- q	vith a maximum of f uestion covering all	the topics under a module.	
• • SI No	There will be two full questions (w Each full question will have sub- q The students will have to answer f Title of the Book	vith a maximum of f uestion covering all five full questions, so Name of the Author/s	the topics under a module. electing one full question from ea Name of the Publisher	ch module Edition and
• • SI No	There will be two full questions (w Each full question will have sub- q The students will have to answer t Title of the Book ook/s Designing for Manufacture	vith a maximum of f uestion covering all five full questions, so Name of the Author/s Peck H	the topics under a module. electing one full question from ea	ch module Edition and
• • SI No Textbo	There will be two full questions (w Each full question will have sub- q The students will have to answer f Title of the Book ook/s	vith a maximum of f uestion covering all five full questions, so Name of the Author/s	the topics under a module. electing one full question from ea Name of the Publisher	ch module Edition and Year
• SI No Textbo	There will be two full questions (w Each full question will have sub- q The students will have to answer f Title of the Book Designing for Manufacture Engineering Design: A Materials and processing	vith a maximum of f uestion covering all five full questions, so Name of the Author/s Peck H	the topics under a module. electing one full question from ea Name of the Publisher Pitman Publications	ch module Edition and Year 1983
• • • • • • • • • • • • • • • • • • •	There will be two full questions (w Each full question will have sub- q The students will have to answer the Title of the Book Title of the Book Designing for Manufacture Engineering Design: A Materials and processing Approach	vith a maximum of f uestion covering all five full questions, s Name of the Author/s Peck H Dieter, G.E.	the topics under a module. electing one full question from ea Name of the Publisher Pitman Publications McGraw Hill Co.Ltd	ch module Edition and Year 1983 2000
• • • • • • • • • • • • • • • • • • •	There will be two full questions (w Each full question will have sub- q The students will have to answer f Title of the Book Designing for Manufacture Engineering Design: A Materials and processing Approach Handbook of Products Design	vith a maximum of f uestion covering all five full questions, s Name of the Author/s Peck H Dieter, G.E.	the topics under a module. electing one full question from ea Name of the Publisher Pitman Publications McGraw Hill Co.Ltd	ch module Edition and Year 1983 2000
• • • • • • • • • • • • • • • • • • •	There will be two full questions (w Each full question will have sub- q The students will have to answer the students will have to answer the Title of the Book Title of the Book Designing for Manufacture Engineering Design: A Materials and processing Approach Handbook of Products Design for Manufacturing: A Practical Guide to Low-cost Production Ence Books	vith a maximum of f uestion covering all five full questions, s Name of the Author/s Peck H Dieter, G.E. Bralla, James G.	the topics under a module. electing one full question from ea Name of the Publisher Pitman Publications McGraw Hill Co.Ltd McGraw Hill, New York	ch module Edition and Year 1983 2000 1986
• • • • • • • • • • • • • • • • • • •	There will be two full questions (w Each full question will have sub- q The students will have to answer f Title of the Book Designing for Manufacture Engineering Design: A Materials and processing Approach Handbook of Products Design for Manufacturing: A Practical Guide to Low-cost Production	vith a maximum of f uestion covering all five full questions, s Name of the Author/s Peck H Dieter, G.E.	the topics under a module. electing one full question from ea Name of the Publisher Pitman Publications McGraw Hill Co.Ltd	ch module Edition and Year 1983 2000
SI No Textbo 1 2 3 Refere	There will be two full questions (w Each full question will have sub- q The students will have to answer the students will have to answer the Title of the Book Title of the Book Designing for Manufacture Engineering Design: A Materials and processing Approach Handbook of Products Design for Manufacturing: A Practical Guide to Low-cost Production Ence Books	vith a maximum of f uestion covering all five full questions, s Name of the Author/s Peck H Dieter, G.E. Bralla, James G.	the topics under a module. electing one full question from ea Name of the Publisher Pitman Publications McGraw Hill Co.Ltd McGraw Hill, New York Pearson Education, Inc., New	ch module Edition and Year 1983 2000 1986

Kalandar Saheb,

S.D and Prabhakar, O.

Trucks, H.E.

Linberg, Roy A.

ISPE

U.S.A.

Mich., Dearborn, SME

Allyn and Bacon, Boston,

1999

2nd ed.,1987

4th ed., 1990

B. E. MECHANICAL ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER – VII				
Professional Elective 2				
	AUTOMATION & RO	BOTICS		
Course Code	18ME732	CIE Marks	40	
Teaching Hours /Week (L:T:P) 3:2:0 SEE Marks 60				
Credits	03	Exam Hours	03	

Course Learning Objectives:

- To identify potential areas for automation and justify need for automation.
- To select suitable major control components required to automate a process or an activity
- To study the various parts of robots and fields of robotics.
- To study the various kinematics and inverse kinematics of robots.
- To study the control of robots for some specific applications.

Module-1:

Introduction to automation:

Basic elements of an automated system, advanced automation functions, levels of automation, process industries versus discrete manufacturing industries, continuous versus discrete control, computer process control. Hardware components for automation and process control, sensors, actuators, analog to digital converters, digital to analog converters, input/output devices for discrete data

Module-2:

Automated production lines:

Fundamentals of automated production lines, application of automated production lines, analysis of transfer lines, automated assembly systems, fundamentals of automated assembly systems, quantitative analysis of assembly systems, automatic identification methods, barcode technology, radio frequency identification, other AIDC technologies

Module-3: Industrial Robotics

Robotic configuration, robot anatomy and related attributes, robot control systems, end effectors, sensors in robotics, industrial robot applications, robot accuracy and repeatability, different types of robots, various generations of robots, degrees of freedom – Asimov's laws of robotics, dynamic stabilization of robots.

Module-4: Spatial descriptions and transformations

Robot actuators and Feedback components: Actuators: Pneumatic, Hydraulic actuators, electric & stepper motors, comparison. Position sensors –potentiometers, resolvers, encoders –Velocity sensors, Tactile sensors, Proximity sensors. Manipulator Kinematics: Homogeneous transformations as applicable to rotation and translation -D-H notation, Forward and inverse kinematics.

Module-5: Robot programming

Introduction, levels of robot programming, requirements of robot programming language, problems pertaining to robot programming languages, offline programming systems, central issues in OLP systems, automating subtasks in OLP systems, simple programs on robot applications.

Course Outcomes: At the end of the course, the student will be able to:

CO1: Translate and simulate a real time activity using modern tools and discuss the Benefits of automation. CO2: Identify suitable automation hardware for the given application.

CO3: Recommend appropriate modelling and simulation tool for the given manufacturing Application.

CO4: Explain the basic principles of Robotic technology, configurations, control and Programming of Robots.

CO5: Explain the basic principles of programming and apply it for typical Pick & place, Loading & unloading and palletizing applications

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.

- There will be two full questions (with a maximum of four sub- questions) from each module.
- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.

SI. No.	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year
Textboo	k/s			
1	Computer Integrated Manufacturing	Mikell P. Groover	Pearson	3rd edition, 2009
2	Introduction to robotics mechanics and control	John J. Craig	Pearson	3rd edition, 2009
Referen	ce Books			
1	Robotics for Engineers	Yoram Koren	McGraw Hill International	1st edition, 1985.
2	Industrial Robotics	Weiss, Nagel	McGraw Hill International	2nd edition, 2012
3	Robotic Engineering - An Integrated approach	Klafter, Chmielewski and Negin	РНІ	1st edition, 2009
4	Computer Based Industrial Control	Krishna Kant	EEE-PHI	2nd edition,2010
5	An Introduction to Automated Process Planning System	Tiess Chiu Chang & Richard A. Wysk.		

B. E. MECHANICAL ENGINEERING					
Choice Based Credit System (CBCS) and Outcome Based Education (OBE)					
SEMESTER – VII					
	Professional E	lective 2			
	COMPUTATIONAL FL	UID DYNAMICS			
Course Code	Course Code 18ME733 CIE Marks 40				
Teaching Hours /Week (L:T:P) 3:0:0 SEE Marks 60					
Credits 03 Exam Hours 03					

Course Learning Objectives:

- Study the governing equations of fluid dynamics
- Learn how to formulate and solve Euler's equation of motion.
- Become skilled at Representation of Functions on Computer
- Solve computational problems related to fluid flows

Module-1

Introduction to CFD and Governing Equations

Need of CFD as tool, role in R&D, continuum, material or substantial derivative or total derivative, gradient, divergence and curl operators, Linearity, Principle of Superposition. Derivation of Navier-Stokes equations in control volume (integral form) and partial differential form, Euler equations (governing inviscid equations). Mathematical classification of PDE (Hyperbolic, Parabolic, Elliptic). Method of characteristics, Introduction to Riemann Problem and Solution Techniques.

Module-2

One-dimensional Euler's equation

Conservative, Non-conservative form and primitive variable forms of Governing equations. Flux Jacobian Is there a systematic way to diagona lize '**A**'. Eigen values and Eigenvectors of Flux Jacobian. Decoupling of Governing equations, introduction of characteristic variables. Relation between the two non-conservative forms. Conditions for genuinely nonlinear characteristics of the flux Jacobian.

Introduction to Turbulence Modelling: Derivation of RANS equations and k-epsilon model.

Module-3

Representation of Functions on Computer

Need for representation of functions, Box Function, Hat Function, and Representation of sinx using hat functions: Aliasing, high frequency, low frequency. Representation error as a global error. Derivatives of hat functions, Haar functions, Machine Epsilon. Using Taylor series for representation of Derivatives.

Module-4

Finite difference method – Applied to Linear Convection equation, Laplace Equations, Convection Diffusion equations, Burgers equations, modified equations. Explicit methods and Implicit methods – as applied to applied to linear convection equation, Laplace equations, convection-diffusion equation^o FTCS, FTFS, FTBS, CTCS • Jacobi Method, Gauss-Siedel, Successive Over Relaxation Method, TDMA• Von Naumann stability (linear stability) analysis. Upwind Method in Finite Difference method.

Module-5

Finite volume method Finite volume method. Finding the flux at interface.

Central schemes - Lax-Friedrichs Method, Lax-Wendroff Method, Two-Step Lax-Wendroff Method and Mac Cormack Method

Upwind Method in Finite Volume methods - Flux Splitting Method Steger and Warming, vanLeer, Roe's Method and finding Roe's Averages.

Course Outcomes:

At the end of the course the student will be able to:

CO1: Understand mathematical characteristics of partial differential

equations.

CO2: Explain how to classify and computationally solve Euler and Navier-Stokes equations.

- CO3: Make use of the concepts like accuracy, stability, consistency of numerical methods for the governing equations.
- CO4: Identify and implement numerical techniques for space and time integration of partial differential equations.
- CO5: Conduct numerical experiments and carry out data analysis.

CO6: Acquire basic skills on programming of numerical methods used to solve the Governing equations.

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.
- There will be two full questions (with a maximum of four sub- questions) from each module.
- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.

SI. No.	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year
Textbo	ook/s	•		
1	Computational Fluid Dynamics	T.j.chung	Cambridge University Press	
2	Computational fluid dynamics and heat transfer	Ghoshdastidar	Cengage learning	2017
3	Numerical Computation of Internal and External Flows: The Fundamentals of Computational Fluid Dynamics – Vol 1 & Vol 2	nternal and External Flows: The Fundamentals of Computational Charles Hirsch Butterworth- Heinemann		2007
4	Numerical Heat Transfer and Fluid Flow	SuhasPatankar	Taylor and Francis Publisher	
5	Introduction Computational Fluid Dynamics -Development, Application and Analysis	Atul Sharma	Wiely Publisher	
Refere	nce Books	1		1
1	Computational fluid mechanics and heat transfer	Pletcher, r. H., Tannehill, j. C., Anderson, d.	Crc press, ISBN 9781591690375	3rd ed, 2011
2	Fundamentals of engineering numerical analysis	Moin, p	Cambridge university press, , ISBN 9780521805261	2nd ed, 2010
3	Numerical methods for engineering application	Ferziger, j. H	Wiley	2nd ed, 1998
4	Computational methods for fluid dynamics	Ferziger, j. H., Peric, m	Springer	3rd ed
5	Numerical methods for conservation laws	eth Zurich, birkhauser		pp-199
6	Practical Introduction	Eleuterio F Toro	Springer	

B. E. MECHANICAL ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER – VII

Professional Elective 2

TOTAL QUALITY MANAGEMENT				
Course Code	18ME734	CIE Marks	40	
Teaching Hours /Week (L:T:P)	3:0:0	SEE Marks	60	
Credits	03	Exam Hours	03	

Course Learning Objectives:

- Understand various approaches to TQM
- Understand the characteristics of quality leader and his role.
- Develop feedback and suggestion systems for quality management.
- Enhance the knowledge in Tools and Techniques of quality management.

Module-1

Principles and Practice: Definition, basic approach, gurus of TQM, TQM Framework, awareness, defining quality, historical review, obstacles, benefits of TQM. Quality Management Systems: Introduction, benefits of ISO registration, ISO 9000 series of standards, ISO 9001 requirements.

Module-2

Leadership: Definition, characteristics of quality leaders, leadership concept, characteristics of effective people, ethics, the Deming philosophy, role of TQM leaders, implementation, core values, concepts and framework, strategic planning communication, decision making,

Module-3

Customer Satisfaction and Customer Involvement: Customer Satisfaction: customer and customer perception of quality, feedback, using customer complaints, service quality, translating needs into requirements, customer retention, case studies. Employee Involvement – Motivation, employee surveys, empowerment, teams, suggestion system, recognition and reward, gain sharing, performance appraisal, unions and employee involvement, case studies.

Module-4

Continuous Process Improvement: process, the Juran trilogy, improvement strategies, types of problems, the PDSA Cycle, problem-solving methods, Kaizen, reengineering, six sigma, case studies. Statistical Process Control: Pareto diagram, process flow diagram, cause and effect diagram, check sheets, histograms, statistical fundamentals, Control charts, state of control, out of control process, control charts for variables, control charts for attributes, scatter diagrams, case studies.

Module-5

Total Productive Maintenance (TPM): Definition, Types of Maintenance, Steps in introduction of TPM in an organization, Pillars of TPM – 5S, Jishu Hozen, Quality Maintenance, Planned Maintenance.

Quality by Design (QbD): Definition, Key components of QbD, Role of QbD in Pharmaceutical Industry, Benefits and Challenges of QbD.

Environmental Management Systems (EMS): Definition, Basic EMS, EMS under ISO 14001, Costs and Benefits of EMS.

Course Outcomes: At the end of the course, the student will be able to:

CO1: Explain the various approaches of TQM

CO2: Infer the customer perception of quality

CO3: Analyse customer needs and perceptions to design feedback systems.

CO4: Apply statistical tools for continuous improvement of systems

CO5: Apply the tools and technique for effective implementation of TQM.

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.
- There will be two full questions (with a maximum of four sub- questions) from each module.
- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module

SI No	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year		
Textbo	ok/s					
1	Total Quality Management	Dale H. Besterfield	Pearson Education India,	Edition 03. ISBN: 8129702606,		
2	Total Quality Management for Engineers	M. Zairi	Wood head Publishing	ISBN:185573024 3		
Referer	Reference Books					
1	Managing for Quality and Performance Excellence	James R. Evans and William M Lindsay	Cengage Learning.	9th edition		
2	Four revolutions in management	Shoji Shiba, Alan Graham, David Walden	Oregon	1990		
3	Organizational Excellence through TQM	H. Lal	New age Publications	2008		
4	Engineering Optimization Methods and Applications	A Ravindran, K, M. Ragsdell	Willey India Private Limited	2nd Edition,2006		
5	Introduction to Operations Research- Concepts and Cases	F.S. Hillier. G.J. Lieberman	Tata McGraw Hill	9 th Edition, 2010		

Choice Based Credit Course Code Teaching Hours /Week (L:T:P) Credits Course Learning Objectives: To enable the students to un organization with a quantitat To enable the students to un optimal solutions to proble machinery. Module-1 ntroduction: Evolution of OR, Defin	ive basis of decision making. understand the importance	2 H CIE Marks SEE Marks Exam Hours	40 60 03
 Teaching Hours /Week (L:T:P) Credits Course Learning Objectives: To enable the students to un organization with a quantitat To enable the students to un optimal solutions to proble machinery. 	Professional Elective 2 OPERATIONS RESEARC 18ME735 3:0:0 03 nderstand the scientific meth ive basis of decision making. understand the importance	H CIE Marks SEE Marks Exam Hours	60
 Teaching Hours /Week (L:T:P) Credits Course Learning Objectives: To enable the students to un organization with a quantitat To enable the students to un optimal solutions to proble machinery. 	OPERATIONS RESEARC 18ME735 3:0:0 03 Inderstand the scientific meth sive basis of decision making. understand the importance	H CIE Marks SEE Marks Exam Hours	60
 Teaching Hours /Week (L:T:P) Credits Course Learning Objectives: To enable the students to un organization with a quantitat To enable the students to un optimal solutions to proble machinery. 	18ME735 3:0:0 03 inderstand the scientific meth ive basis of decision making. understand the importance	CIE Marks SEE Marks Exam Hours	60
 Teaching Hours /Week (L:T:P) Credits Course Learning Objectives: To enable the students to un organization with a quantitat To enable the students to un optimal solutions to proble machinery. 	3:0:0 03 Inderstand the scientific meth ive basis of decision making. understand the importance	SEE Marks Exam Hours	60
 Credits Course Learning Objectives: To enable the students to un organization with a quantitat To enable the students to u optimal solutions to proble machinery. 	03 nderstand the scientific meth tive basis of decision making. understand the importance	Exam Hours	
 Course Learning Objectives: To enable the students to un organization with a quantitat To enable the students to u optimal solutions to proble machinery. Module-1 	nderstand the scientific meth ive basis of decision making. understand the importance		00
 To enable the students to un organization with a quantitat To enable the students to un optimal solutions to proble machinery. 	ive basis of decision making. understand the importance	ods of providing various of	
Nodule-1			niques in finding
Characteristics and limitations of OF PP-Formulation of problems as L.P.F Module-2 PP: Simplex method, Canonical and folutions to LPP by Simplex method	R, models used in OR, Linea P. Solutions to LPP by graphic d Standard form of LP prob d, Big-M Method and two-p	r Programming Problem cal method (Two Variables plem, slack, surplus and a shase Simplex Method, D	(LPP), Generalized). artificial variables
Concept of Duality, writing Dual of giv	ven LPP. Solutions to L.P.P by	Dual Simplex Method.	
ransportation Problem: Formulation	n of transportation problem	types initial basis fassi	hla colution using
pplication of transportation probler by Hungarian method, Special cas problems. Travelling Salesman Proble by Little's method. Numerical Probler	ses in assignment problem em (TSP). Difference betwee	ns, unbalanced, Maximiz	ation assignment
/odule-4			
Network analysis: Introduction, Cons and AOA diagrams; Critical path meth loats in networks, PERT networks, completion time of project; Cost ar Queuing systems and their characte ee's notation of Queuing, empirical of	hod to find the expected con determining the probabilit nalysis in networks. Crashing eristics, Pure-birth and Pure	npletion time of a project y of completing a proje g of networks- Problems. -death models (only equ	, determination or ct, predicting the Queuing Theory ations), Kendall 8
Aodule-5			
Same Theory: Definition, Pure Strate Dominance, Solution of games with Arithmetic method, Solution of 2X Sequencing: Basic assumptions, John ules, sequencing using Johnson's r nachines. Sequencing of2 jobs on 'm	h Saddle point. Mixed Strat (n m and mX2 games by g nson's algorithm, sequencing rule-'n' jobs on 2 machines	tegy problems. Solution graphical method. Form g 'n' jobs on single mach , 'n' jobs on 3 machine:	of 2X2 games by ulation of games nine using priority
Course Outcomes: At the end of the	course, the student will be at	ole to:	
CO1: Understand the meaning, defini CO2: Formulate as L.P.P and derive of Simplex method, Big-M method CO3: Formulate as Transportation ransportation,	ptimal solutions to linear pro and Dual Simplex method.	gramming problems by gr	aphical method,

Assignment and travelling salesman problems.

- CO4: Solve problems on game theory for pure and mixed strategy under competitive environment.
- CO5: Solve waiting line problems for M/M/1 and M/M/K queuing models.
- CO6: Construct network diagrams and determine critical path, floats for deterministic and PERT networks including crashing of Networks
- CO7: Determine minimum processing times for sequencing of n jobs-2 machines, n jobs-3 machines, n jobs-m machines and 2 jobs-n machines using Johnson's algorithm.

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.
- There will be two full questions (with a maximum of four sub- questions) from each module.
- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.

Sl. No.	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year
Textboo	k/s			
1	Operations Research	P K Gupta and D S Hira	S. Chand and Company LTD. Publications, New Delhi	2007
2	Operations Research, An Introduction	Hamdy A. Taha	PHI Private Limited	Seventh Edition, 2006
Reference	ce Books			
1	Operations Research, Theory and Applications	J K Sharma	Trinity Press, Laxmi Publications Pvt.Ltd.	Sixth Edition, 2016
2	Operations Research	Paneerselva n	PHI	
3	Operations Research	A M Natarajan, P Balasubram ani	Pearson Education,	2005
4	Introduction to Operations Research	Hillier and Lieberman	McGraw Hill	8thEd

B. E. MECHANICAL ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER – VII					
Professional Elective 3					
ADDITIVE MANUFACTURING					
Course Code	18ME741	CIE Marks	40		
Teaching Hours /Week (L:T:P) 3:0:0 SEE Marks 60					
Credits 03 Exam Hours 03					
Course Learning Objectives:		· · · · · ·			

- To know the principle methods, areas of usage, possibilities and limitations of the Additive Manufacturing technologies.
- To be familiar with the characteristics of the different materials those are used in Additive Manufacturing.
- To know the principles of polymerization and powder metallurgy process, extrusion-based system printing processes, sheet lamination processes, beam deposition processes, direct write technologies and Direct Digital Manufacturing.
- To get exposed to process selection, software issues and post processing.

Module-1

Introduction and basic principles: Need for Additive Manufacturing, Generic AM process, stereoli tho graphy or 3dprinting, rapid proto typing the benefits of AM, distinction between AM and CNC machining, other related technologies- reverse engineering technology.

Development of Additive Manufacturing Technology: Introduction, computers, computer-aidedde sign technology, other associated technologies, the use of layers, classification of AM processes, metals ystems, hybrid systems, milestones in AM development.

Additive Manufacturing Process chain: Introduction, the eight steps in additive manufacture, variations from one AM machine to another ,metal systems, maintenance of equipment, materials handling issues, design for AM, and application areas.

Module-2

Photo polymerization processes: Stereolitho graphy (SL), Materials, SL resin curing process, Micro-stereoli thography, Process Benefits and Drawbacks, Applications of Photo polymerization Processes.

Powder bedfusion processes: Introduction, Selective laser Sintering (SLS), Materials, Powder fusion mechanism, SLS Metal and ceramic part creation, Electron Beam melting (EBM), Process Benefits and Drawbacks, Applications of Powder Bed Fusion Processes.

Extrusion-based systems: Fused Deposition Modelling (FDM), Principles, Materials, Plotting and path control, Bio-Extrusion, Process Benefits and Drawbacks, Applications of Extrusion-Based Processes.

Module-3

Printing Processes: evolution of printing as an additive manufacturing process, research achievements in printing deposition, technical challenges of printing, printing process modeling, material modification methods, three-dimensional printing, advantages of binder printing

Sheet Lamination Processes: Materials, Laminated Object Manufacturing (LOM), Ultrasonic Consolidation (UC), Gluing, Thermal bonding, LOM and UC applications.

Beam Deposition Processes: introduction, general beam deposition process, description material delivery, BD systems , process parameters, typical materials and microstructure, processing–structure–properties relationships, BD benefits and drawbacks.

Direct Write Technologies: Background ,ink -basedDW,laser transfer, DW thermals pray,DW beam deposition,DW liquid-phase directde position.

Module-4

Guidelines for Process Selection: Introduction, selection methods for apart, challenges of selection, example system for preliminary selection, production planning and control.

Software issues for Additive Manufacturing: Introduction, preparation of cad models – the STL file, problems with STL files, STL file manipulation.

Post- Processing: Support material removal, surface texture improvements, preparation for use as a pattern, property enhancements using non-thermal techniques and thermal techniques.

Module-5

The use of multiple materials in additive manufacturing: Introduction, multiple material approaches, discrete multiple material processes, porous multiple material processes, blended multiple material processes, commercial applications using multiple materials, future directions.

AM Applications: Functional models, Pattern for investment and vacuum casting, Medical models, art models, Engineering analysis models, Rapid tooling, new materials development, Bi-metallic parts, Remanufacturing. Application: Examples for Aerospace, defense, automobile, Bio-medical and general engineering industries.

Direct digital manufacturing: Align Technology, siemens and phonak, DDM drivers, manufacturing vs. prototyping, life- cycle costing, future of direct digital manufacturing.

Course Outcomes: At the end of the course the student will be able to:

- CO1: Demonstrate the knowledge of the broad range of AM processes, devices, capabilities and materials that are available.
- CO2: Demonstrate the knowledge of the broad range of AM processes, devices, capabilities and materials that are available.
- CO3: Understand the various software tools, processes and techniques that enable advanced/additive manufacturing.
- CO4: Apply the concepts of additive manufacturing to design and create components that satisfy product development/prototyping requirements, using advanced/additive manufacturing devices and processes.
- CO6: Understand characterization techniques in additive manufacturing.

CO7: Understand the latest trends and business opportunities in additive manufacturing.

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.
- There will be two full questions (with a maximum of four sub- questions) from each module.
- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.

Sl. No. Textbook	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year		
1	Additive Manufacturing Technologies Rapid Prototyping to Direct Digital Manufacturing	I. Gibson l D. W. Rosen l B. Stucker	Springer New York Heidelberg Dordrecht, London	ISBN: 978-1- 4419-1119-3 e-ISBN: 978- 1-4419- 1120-9 DOI 10.1007/978 -1-4419- 1120-9		
Reference	Reference Books					
1	"Rapid Prototyping: Principles & Applications	Chua Chee Kai, Leong Kah Fai	World Scientific	2003		
2	Rapid Prototyping: Theory & Practice	Ali K. Kamrani,	Springer	2006		

		EmandAbouel Nasr,		
3	Rapid Manufacturing: The Technologies and Applications of Rapid Prototyping and Rapid Tooling"	D.T. Pham, S.S. Dimov	Springer	2001
4	Rapid Prototyping: Principles and Applications in Manufacturing	RafiqNooran	John Wiley & Sons	2006
5	Additive Manufacturing Technology	Hari Prasad, A.V.Suresh	Cengage	2019
6	Understanding additive manufacturing: rapid prototyping, rapid tooling, rapid manufacturing	Andreas Gebhardt	Hanser Publishers	2011

B. E. MECHANICAL ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER – VII Professional Elective 3					
EMERGING	SUSTAINABLE BUILDING C	OOLING TECHNOLOGIES			
Course Code	18ME742	CIE Marks	40		
Teaching Hours /Week (L:T:P) 3:0:0 SEE Marks 60					
Credits 03 Exam Hours 03					

Course Learning Objectives:

- To provide an overview of emerging delivery systems for high performance green buildings and the basis on which their sustainability can be evaluated
- To know the concepts of calculations of heating and cooling loads and the related economics.
- To learn the importance of green fuels and its impact on environment.
- To expose the students to sustainable cooling technologies.

Module-1

Social and Environmental Issues related to conventional Refrigeration and Air conditioning: Climate Change and energy poverty implications of energy consumption and refrigerants use by conventional Vapor-Compression based RAC technologies, Global and Indian environmental, energy efficiency and green building policies, laws and rules warranting a trajectory shift in the RAC economy, Introduction to Thermal comfort as an 'ends' and cooling systems as a 'means', Socio-economic and environmental benefits of a Negawatt approach to energy conservation vs. a Megawatt approach towards power generation.

Module-2

Thermal Comfort, Climate Analysis and Psychrometry: The 'human thermal comfort' lens and its implications for cooling system design, Progressive models for addressing human thermal comfort needs, Thermodynamics of human body, Factors affecting human comfort, Introduction to the ASHRAE Std. 55, Adaptive Comfort Model and the Indian Model for Adaptive Comfort (IMAC) and its implications for mitigating climate change and energy consumption from cooling technologies, Tools for predicting thermal comfort in buildings, Principles and tools for climate analysis, Composition of Psychrometric Charts, Psychrometric processes of conventional and sustainable cooling technologies and representation on psychrometric chart, Application of psychrometry to design conventional and sustainable cooling technologies.

Indoor Air Quality and Building Cooling Load Modelling:

Addressing trade-offs between indoor air quality requirements, daylighting needs, and solar heat gain

Module-3

Refrigeration Systems and Refrigerants:

Thermodynamics of Vapor Compression Refrigeration (VCR) and Vapor Absorption Machine (VAM) Cycles, Equipment used in commercial and residential VCR and VAM systems, Physical, Chemical, Thermodynamic and Environmental properties of Refrigerants and Refrigerant mixtures (zeotropic and azeotropic mixtures) used in conventional VCR system, Absorbent – Refrigerant combinations (Water-Ammonia and Lithium-Bromide) used in VAM systems, Physical, Chemical, Thermodynamic and Environmental properties of emerging Natural Refrigerants for VCR systems.

Module-4

Air conditioning:

Air conditioning demand scenarios for India and associated health, social justice, energy access, and environmental Implications for its peoples and communities, Potential sustainable air conditioning scenarios for India, Heat transfer and psychrometric principles of air conditioning cycles, Engineering principles of air conditioning components, Air conditioning coefficient-of-performance calculation, Energy efficient air conditioning system, Energy and greenhouse gas emissions-based performance comparison of natural refrigerant and f-gas based air conditioners.

Module-5

Sustainable Cooling Technologies:

Radical social justice fostering, energy conservation, and climate change mitigation potential of natural cooling, Design principles of natural and sustainable cooling systems, Science and engineering design principles of a) Direct, Indirect, and Hybrid (Direct-Indirect and DX) Evaporative Cooling technology, b) Structure Cooling, c) Radiant Cooling Systems, and d) Solar VAM technology, Basic equipment sizing calculations, System performance assessment methods, Comparative energy consumption, greenhouse gas emissions and life-cycle cost case studies for residential and commercial applications of conventional and sustainable cooling technologies.

Course Outcomes: At the end of the course, the student will be able to:

- CO1: Empathize with sustainable cooling as a means of enhancing social justice in India and mitigating climate change through their intellectual capabilities and ethical orientation
- CO2: Compute and Interpret cooling and heating loads in a building and how they could be efficiently managed by using building energy modelling software
- CO3: Estimate the performance of airconditioning systems using the principles of thermodynamics, heat transfer, and psychometry

CO4: Calculate and interpret the energy, cost, and greenhouse gas emissions performance of conventional

and sustainable cooling technologies.

Co6: Conduct building and sustainable cooling modelling projects on a sophisticated building energy modelling software.

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.
- There will be two full questions (with a maximum of four sub- questions) from each module.
- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.

SI. No.	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year
Textbo	ok/s			
1	Refrigeration and Airconditioning	C P Arora	Tata McGraw Hill	3 rd Edition
2	Heating, Ventilating and Airconditioning	Faye C McQuiston, Jerald D. Parker, Jeffrey D. Spitler	Wiley Indian Private Ltd.	
Refere	nce Books			
1	Radiant Heating and Cooling Handbook	Richard D. Watson	McGraw-Hill Publication	2002
	tps://www.accessengineeringlibrary. ook#p2000a97e9970iii001	com/browse/radian	t-heating-and-cooling-	
2	Evaporative Cooling		CAREL	
Link: <u>ht</u>	tp://www.carel.com/-evaporative-co	oling-book		

B. E. MECHANICAL ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER – VII Professional Elective 3					
THEORYOF PLASTICITY					
Course Code	18ME743	CIE Marks	40		
Teaching Hours /Week (L:T:P) 3:0:0 SEE Marks 60					
Credits 03 Exam Hours 03					
Course Learning Objectives:	· ·	· · ·			

rse Learning Objectives:

- To introduce the concepts of Plasticity and mechanism of plastic deformation in metals.
- To expose the students to elasto-plastic problems involving plastic deformation of beams and bars.
- To introduce the concepts of slip line field theory.

Module-1

Brief review of fundamentals of elasticity: Concept of stress, stress invariants, principal Stresses, octahedral normal and shear stresses, spherical and deviatoric stress, stress transformation; concept of strain, engineering and natural strains, octahedral strain, deviator and spherical strain tensors, strain rate and strain rate tensor, cubical dilation, generalized Hooke's law, numerical problems.

Module-2

Plastic Deformation of Metals: Crystalline structure in metals, mechanism of plastic deformation, factors affecting plastic deformation, strain hardening, recovery, re crystallization and grain growth, flow figures or Luder's cubes.

Yield Criteria: Introduction, yield or plasticity conditions, Von Mises and Tresca criterion, geometrical representation vield surface vield locus (two-dimensional stress space) experimental evidence for vield Module-3

Stress Strain Relations: Idealised stress-strain diagrams for different material models, empirical equations, Levy-Von Mises equation, Prandtl -Reuss and Saint Venant theory, experimental verification of Saint Venant's theory of plastic flow. Concept of plastic potential, maximum work hypothesis, mechanical work for deforming a plastic substance.

Module-4

Bending of Beams: Stages of plastic yielding, analysis of stresses, linear and nonlinear stress strain curve, problems.

Torsion of Bars: Introduction, plastic torsion of a circular bar, elastic perfectly plastic material, elastic work hardening of material, problems.

Module-5

Slip Line Field Theory: Introduction, basic equations for incompressible two-dimensional flows, continuity equations, stresses in conditions of plain strain, convention for slip lines, geometry of slip line field, properties of the slip lines, construction of slip line nets.

Course Outcomes: At the end of the course the student will be able to:

CO1: Understand stress, strain, deformations, relation between stress and strain and plastic deformation in solids.

CO2: Understand plastic stress-strain relations and associated flow rules.

CO3: Perform stress analysis in beams and bars including Material nonlinearity.

CO4: Analyze the yielding of a material according to different yield theory for a given state of stress.

CO5: Interpret the importance of plastic deformation of metals in engineering problems.

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.
- There will be two full questions (with a maximum of four sub- questions) from each module.

- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.

SI. No.	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year			
Textb	Textbook/s						
1	Theory of Plasticity	Chakraborty	Elsevier	3rd Edition			
2	Theory of Plasticity and Metal forming Process	Sadhu Singh	Khanna Publishers, Delhi				
Refere	ence Books						
1	Engineering Plasticity-Theory and Application to Metal Forming Process	R.A.C. Slater	McMillan Press Ltd.				
2	Basic Engineering Plasticity	DWA Rees	Elsevier	1st Edition			
3	Engineering Plasticity	W. Johnson and P. B. Mellor	Van NoStrand Co. Ltd	2000			
4	Advanced Mechanics of solids	L. S. Srinath	Tata Mc. Graw Hill	2009			

B. E. MECHANICAL ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER – VII Professional Elective 3					
MECHATRONICS					
Course Code 18ME744 CIE Marks 40					
Teaching Hours /Week (L:T:P)3:0:0SEE Marks60					
Credits 03 Exam Hours 03					
	Professional Electi MECHATRONIC 8ME744 :0:0	Professional Elective 3 MECHATRONICS 8ME744 CIE Marks :0:0 SEE Marks			

Course Learning Objectives:

- To acquire a strong foundation in science and focus in mechanical, electronics, control, software, and computer engineering, and a solid command of the newest technologies.
- To understand the evolution and development of Mechatronics as a discipline.
- To substantiate the need for interdisciplinary study in technology education
- To understand the applications of microprocessors in various systems and to know the functions of each element.
- To demonstrate the integration philosophy in view of Mechatronics technology
- To be able to work efficiently in multidisciplinary teams.

Module-1

Introduction: Scope and elements of mechatronics, mechatronics design process, measurement system, requirements and types of control systems, feedback principle, Basic elements of feedback control systems, Classification of control system. Examples of Mechatronics Systems such as Automatic Car Park system, Engine management system, Antilock braking system (ABS) control, Automatic washing machine.

Transducers and sensors: Definition and classification of transducers, Difference between transducer and sensor, Definition and classification of sensors, Principle of working and applications of light sensors, Potentiometers, LVDT, Capacitance sensors, force and pressure sensors, Strain gauges, temperature sensors, proximity switches and Hall Effect sensors.

Module-2

Signal Conditioning: Introduction – Hardware – Digital I/O, Analog to digital conversions, resolution, Filtering Noise using passive components – Registers, capacitors, amplifying signals using OP amps. Digital Signal Processing – Digital to Analog conversion, Low pass, high pass, notch filtering. Data acquisition systems (DAQS), data loggers, Supervisory control and data acquisition (SCADA), Communication methods.

Electro Mechanical Drives:Relays and Solenoids – Stepper Motors – DC brushed motors – DC brushless motors – DC servo motors – 4-quadrant servo drives, PWM's – Pulse Width Modulation.

Module-3

Microprocessor & Microcontrollers: Introduction, Microprocessor systems, Basic elements of control systems, Microcontrollers, Difference between Microprocessor and Microcontrollers.

Microprocessor Architecture: Microprocessor architecture and terminology-CPU, memory and address, I/O and Peripheral devices, ALU, Instruction and Program, Assembler, Data Registers, Program Counter, Flags, Fetch cycle, write cycle, state, bus interrupts. Intel's 8085A Microprocessor.

Module-4

Programmable Logic Controller: Introduction to PLCs, Basic structure of PLC, Principle of operation, input and output processing, PLC programming language, ladder diagram, ladder diagrams circuits, timer counters, internal relays, master control, jump control, shift registers, data handling, and manipulations, analogue input and output, selection of PLC for application.

Application of PLC control: Extending and retracting a pneumatic piston using latches, control of two pneumatic pistons, control of process motor, control of vibrating machine, control of process tank, control of conveyer motor etc.

Module-5

Mechatronics in Computer Numerical Control (CNC) machines: Design of modern CNC machines - Machine Elements: Different types of guide ways, Linear Motion guideways. Bearings: anti-friction bearings,

hydrostatic bearing and hydrodynamic bearing. Re-circulating ball screws. Typical elements of open and closed loop control systems. Adaptive controllers for machine tools.

Mechatronics Design process: Stages of design process – Traditional and Mechatronics design concepts – Case studies of Mechatronics systems – Pick and place Robot – Automatic car park barrier.

Course Outcomes: At the end of the course the student will be able to:

CO1: Illustrate various components of Mechatronics systems.

CO2: Assess various control systems used in automation.

CO3: Design and conduct experiments to evaluate the performance of a mechatronics system or component with

respect to specifications, as well as to analyse and interpret data.

CO4: Apply the principles of Mechatronics design to product design.

CO5: Function effectively as members of multidisciplinary teams.

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.
- There will be two full questions (with a maximum of four sub- questions) from each module.
- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.

SI. No.	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year
Textbo	ok/s			
1	Mechatronics-Principles Concepts and Applications	Nitaigour Premchand Mahalik	Tata McGraw Hill	1 st Edition, 2003
2	Mechatronics–Electronic Control Systems in Mechanical and Electrical Engineering,	W.Bolton	Pearson Education	1stEdition, 2005
Refere	nce Books	I		1
1	Mechatronics	HMT Ltd	Tata Mc Graw Hill	1st Edition, 2000 ISBN:978007 4636435
2	Mechatronics: Integrated Mechanical Electronic Systems	K.P. Ramachandran, G.K. Vijayaraghavan, M.S. Balasundaram.	Wiley India Pvt. Ltd. New Delhi	2008
3	Introduction to Mechatronics and Measurement Systems	David G. Aldatore, Michael B. Histand	McGraw-Hill Inc USA	2003
4	Introduction to Robotics: Analysis, Systems, Applications.	Saeed B. Niku,	Person Education	2006
5	Mechatronics System Design	Devdas Shetty, Richard A. kolk	Cengage publishers.	second edition

edit System (CBCS) and Out SEMESTER – VI	come Based Education (OBE)	
PROJECT MANAGEN	MENT	
18ME745	CIE Marks	40
3:0:0	SEE Marks	60
03	Exam Hours	03
	edit System (CBCS) and Out SEMESTER – VI Professional Electi PROJECT MANAGEN 18ME745 3:0:0	3:0:0 SEE Marks

Course Learning Objectives:

- To understand how to break down a complex project into manageable segments and use of effective project management tools and techniques to arrive at solution and ensure that the project meets its deliverables and is completed within budget and on schedule.
- To impart knowledge on various components, phases, and attributes of a project.
- To prepare students to plan, develop, lead, manage, and successfully implement and deliver projects within their chosen practice area.

Module-1

Introduction: Definition of project, characteristics of projects, understand projects, types of projects, scalability of project tools, project roles Project Selection and Prioritization – Strategic planning process, Strategic analysis, strategic objectives, portfolio alignment – identifying potential projects, methods of selecting projects, financial mode / scoring models to select projects, prioritizing projects, securing and negotiating projects.

Module-2

Planning Projects: Defining the project scope, Project scope checklist, Project priorities, Work Breakdown Structure (WBS), Integrating WBS with organisation, coding the WBS for the information system. Scheduling Projects: Purpose of a project schedule, historical development, how project schedules are limited and created, develop project schedules, uncertainty in project schedules, Gantt chart.

Module-3

Resourcing Projects: Abilities needed when resourcing projects, estimate resource needs, creating staffing management plant, project team composition issues, Budgeting Projects: Cost planning, cost estimating, cost budgeting, establishing cost control. Project Risk Planning: Risk Management Planning, risk identification, risk analysis, risk response planning, Project Quality Planning and Project Kick off: Development of quality concepts, project quality management plan, project quality tools, kick off project, baseline and communicate project management plan, using Microsoft Project for project baselines.

Module-4

Performing Projects: Project supply chain management: - Plan purchasing and acquisitions, plan contracting, contact types, project partnering and collaborations, project supply chain management. 28 Project Progress and Results: Project Balanced Scorecard Approach, Internal project, customer, financial issues, Finishing the project: Terminate project early, finish projects on time, secure customer feedback and approval, knowledge management, perform administrative and contract closure.

Module-5

Network Analysis: Introduction, network construction - rules, Fulkerson's rule for numbering the events, AON and AOA diagrams; Critical path method (CPM) to find the expected completion time of a project, floats; PERTfor finding expected duration of an activity and project, determining the probability of completing a project, predicting the completion time of project; crashing of simple projects.

Course Outcomes: At the end of the course the student will be able to:

- CO1: Understand the selection, prioritization and initiation of individual projects and strategic role of project management.
- CO2: Understand the work breakdown structure by integrating it with organization.
- CO3: Understand the scheduling and uncertainty in projects.

CO4: Understand risk management planning using project quality tools.

CO5: Understand the activities like purchasing, acquisitions, contracting, partnering and collaborations related to performing projects.

CO6: Determine project progress and results through balanced scorecard approach

CO7: Draw the network diagram to calculate the duration of the project and reduce it using crashing.

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.
- There will be two full questions (with a maximum of four sub- questions) from each module.
- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.

SI. No.	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year
Textbo	ook/s			
1	Project Management	Timothy J Kloppenborg	Cengage Learning	Edition 2009
2	Project Management -A systems approach to planning scheduling and controlling	Harold kerzner	CBS publication	
3	Project Management	S Choudhury	McGraw Hill Education (India) Pvt. Ltd. New Delhi	2016
Refere	ence Books			
1	Project Management	Pennington Lawrence	Mc Graw Hill	
2	Project Management	A Moder Joseph and Phillips New Yark	Van Nostrand Reinhold	
3	Project Management,	Bhavesh M. Patal	Vikas publishing House	

Choice Based Cr	B. E. MECHANICAL ENGI edit System (CBCS) and Out	NEERING come Based Education (OBE)	
	Open Elective-B (Ser	nester VII)	
	ENERGY AND ENVIRON	IMENT	
Course Code	18ME751	CIE Marks	40
Teaching Hours / Week (L:T:P)	3:0:0	SEE Marks	60
Credits	03	Exam Hours	03
Course Learning Objectives:			
 To understand the fundam 	nentals of energy sources, en	ergy use, energy efficiency, and re	sulting
environmental implication	is of various energy supplies.		
To introduce various aspect	cts of environmental pollutio	n and its control.	
• To understand the causes	and remedies related to soci	al issues like global warming, ozon	e layer
depletion, climate change	etc.		
• To introduce various acts r	related to prevention and cor	ntrol of pollution of water and air,	forest
protection act, wild life pro		•	
Module-1			
Basic Introduction to Energy: Ene	ergy and power, forms of e	nergy, primary energy sources, e	nergy flows
world energy production and cons		-	
energy, Energy production and	-		-
demographics Policy and institution	onal framework, Energy pric	es and affordability, Social and er	nvironmenta
aspects, Investment.			
Module-2			
Energy storage systems: Thermal e Energy Management: Principles of Energy Audit: Purpose, Methodole Certain Energy Intensive Industries	Energy Management, Energo ogy with respect to process	y demand estimation, Energy pricit	ng
Module-3			
Environment: Introduction, Mul	tidisciplinary nature of en	vironmental studies- Definition,	scope and
importance, Need for public aware	eness.		
Ecosystem: Concept, Energy flow	v, Structure and function of	an ecosystem. Food chains, foo	od webs and
ecological pyramids, Forest ecosy	ystem, Grassland ecosystem	, Desert ecosystem and Aquatic	ecosystems
Ecological succession.			
Module-4			
Environmental Pollution: Definitio	n, Cause, effects and contro	I measures of - Air pollution, Wat	ter pollution
Soil pollution, Marine pollution,	Noise pollution, Thermal	pollution and Nuclear hazards,	Solid wast
Management, Disaster manageme	ent Role of an individual in pro	evention of pollution, Pollution cas	se studies.
Module-5	I ^r	. ,	
Social Issues and the Environment	: Climate change, global war	ming, acid rain, ozone laver denle	tion, nuclea
	0.0		
accidents and holocaust Case	Studies Wasteland redar	nalion (onclimenter and wate	te producto
accidents and holocaust. Case			•
Environment Protection Act, Air (I	Prevention and Control of Po	ollution) Act, Water (Prevention a	nd control o
Environment Protection Act, Air (I Pollution) Act, Wildlife Protection	Prevention and Control of Po	ollution) Act, Water (Prevention a	nd control o
Environment Protection Act, Air (I Pollution) Act, Wildlife Protection environmental legislation.	Prevention and Control of Po	ollution) Act, Water (Prevention a	nd control o
Environment Protection Act, Air (I Pollution) Act, Wildlife Protection environmental legislation. Group assignments:	Prevention and Control of Poon Act, Forest Conservatio	ollution) Act, Water (Prevention an on Act, Issues involved in enfo	nd control o prcement o
Environment Protection Act, Air (I Pollution) Act, Wildlife Protection environmental legislation. Group assignments: Assignments related to e-waste	Prevention and Control of Po on Act, Forest Conservation management; Municipal so	bllution) Act, Water (Prevention an on Act, Issues involved in enfo lid waste management; Air pollu	nd control o prcement o ution contro
Environment Protection Act, Air (I Pollution) Act, Wildlife Protection environmental legislation. Group assignments: Assignments related to e-waste systems; Water treatment system	Prevention and Control of Po on Act, Forest Conservation management; Municipal so s; Wastewater treatment pla	bllution) Act, Water (Prevention an on Act, Issues involved in enfo lid waste management; Air pollu nts; Solar heating systems; Solar p	nd control o prcement o ution contro power plants
Environment Protection Act, Air (I Pollution) Act, Wildlife Protection environmental legislation. Group assignments: Assignments related to e-waste	Prevention and Control of Po on Act, Forest Conservation management; Municipal so s; Wastewater treatment pla	bllution) Act, Water (Prevention an on Act, Issues involved in enfo lid waste management; Air pollu nts; Solar heating systems; Solar p	nd control corcement of control contro

CO1: Understand energy scenario, energy sources and their utilization.

- CO2: Understand various methods of energy storage, energy management and economic analysis.
- CO3: Analyse the awareness about environment and eco system.

CO4: Understand the environment pollution along with social issues and acts.

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.
- There will be two full questions (with a maximum of four sub- questions) from each module.
- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.

SI. No.	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year
Textb	pok/s	·	·	
1	Textbook for Environmental Studies for Undergraduate Courses of all Branches of Higher Education		University grant commission and Bharathi Vidyapeeth Institute of environment education and Research, Pune	
2	Energy Management Audit & Conservation- for Module 2	Barun Kumar De	Vrinda Publication	2nd Edition 2010
Refere	ence Books		•	·
1	Energy Management Hand book	Turner, W. C., Doty, S. and Truner, W. C	Fairmont Press	7 th Edition 2009
2	Energy Management	Murphy, W. R	Elsevier	2007
3	Energy Management Principles	Smith, C. B	Pergamum	2007
4	Environment pollution control Engineering	C S Rao	New Age International	reprint 2015, 2nd edition
5	Environmental studies	Benny Joseph	Tata McGraw Hill	2nd edition 2008

B. E. MECHANICAL ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE)

Semester VIII Open Elective B

	AUTOMOTIVE ENGIN	EERING	
Course Code	18ME752	CIE Marks	40
Teaching Hours /Week (L:T:P)	3:0:0	SEE Marks	60
Credits	03	Exam Hours	03

Course Learning Objectives:

- To know layout and arrangement of principal parts of an automobile.
- To understand the working of transmission and brake systems.
- To comprehend operation and working of steering and suspension systems.
- To know the Injection system and its advancements.
- To know the automobile emissions and its effects on environment.

Module-1

ENGINE COMPONENTS AND IT'S PRINCIPLE PARTS: Spark Ignition (SI) & Compression Ignition (CI) engines, cylinder – arrangements and their relatives merits, Liners, Piston, connecting rod, crankshaft, valves, valve actuating mechanisms, valve and port timing diagrams, Types of combustion chambers for S.I.Engine and C.I.Engines, methods of a Swirl generation, engine positioning. Concept of HCCI engines, Hybrid engines, Twin spark engine, Electric car.

COOLING AND LUBRICATION: Cooling requirements, Types of cooling- Thermo siphon system, Forced circulation water cooling system, Water pump, Radiator, Significance of lubrication, Splash and Forced feed system.

Module-2

TRANSMISSION SYSTEMS: Clutch-types and construction, gear boxes- manual and automatic, gear shift mechanisms, Over drive, transfer box, fluid flywheel, torque converter, propeller shaft, slip joints, universal joints. Differential and rear axle, Hotchkiss Drive and Torque Tube Drive.

BRAKES: Types of brakes, mechanical compressed air, vacuum and hydraulic braking systems, construction and working of master and wheel cylinder, brake shoe arrangements, Disk brakes, drum brakes, Antilock – Braking systems, purpose and operation of antilock-braking system, ABS Hydraulic Unit, Rear-wheel antilock, & Numerical.

Module-3

STEERING AND SUSPENSION SYSTEMS: Steering geometry and types of steering gear box-Power Steering, Types of Front Axle, Suspension, Torsion bar suspension systems, leaf spring, coil spring, independent suspension for front wheel and rear wheel, Air suspension system.

IGNITION SYSTEM: Battery Ignition system, Magneto Ignition system, electronic Ignition system.

Module-4

SUPERCHARGERS AND TURBOCHARGERS: Naturally aspirated engines, Forced Induction, Types of superchargers, Turbocharger construction and operation, Intercooler, Turbocharger lag.

FUELS, FUEL SUPPLY SYSTEMS FOR SI AND CI ENGINES: Conventional fuels, Alternative fuels, Normal and Abnormal combustion, Cetane and Octane numbers, Fuel mixture requirements for SI engines, Types of carburetors, C.D.& C.C. carburettors, Multi point and Single point fuel injection systems, fuel transfer pumps, Fuel filters, fuel injection pumps and injectors. Electronic Injection system, Common Rail Direct Injection System.

Module-5

AUTOMOTIVE EMISSION CONTROL SYSTEMS: Different air pollutants, formation of photochemical smog and causes. Automotive emission controls, Controlling crankcase emissions, Controlling evaporative emissions, Cleaning the exhaust gas, Controlling the air-fuel mixture, Controlling the combustion process, Exhaust gas recirculation, Treating the exhaust gas, Air-injection system, Air-aspirator system, Catalytic converter. **EMISSION STANDARDS:** Euro I, II, III and IV norms, Bharat Stage II, III, IV norms. Motor Vehicle Act.

Course Outcomes: At the end of the course, the student will be able to:

- Identify the different parts of an automobile and it's working.
- Understand the working of transmission and braking systems.
- Understand the working of steering and suspension systems and their applications.
- Selection and applications of various types of fuels and injection systems.
 Analyse the cause of automobile emissions, its effects on environment and methods to reduce the emissions.

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.
- There will be two full questions (with a maximum of four sub- questions) from each module.
- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.

SI No	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year
Textbo	ok/s			
1	Automobile engineering Vol I and II	Kirpal Singh	Standard Publishers	12 th Edition 2011
2	Automotive Mechanics	S. Srinivasan	Tata McGraw Hill	2003 2 nd Edition
Referer	nce Books			
1	Automotive Mechanics	William H Crouse & Donald L Anglin	Tata McGraw Hill Publishing Company	10 th Edition 2007
2	Automotive Mechanics: Principles and Practices,	Joseph Heitner	D Van Nostrand Company, Inc	
3	Automobile Engineering	R. B. Gupta	Satya Prakashan	4 th edition 1984.
4	Fundamentals of Automobile Engineering	K.K.Ramalingam	Scitech Publications (India) Pvt. Ltd	

B. E. MECHANICAL ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE)

	Semester VII Open Ele	ective-B	
	INDUSTRIAL SAF	ETY	
Course Code	18ME753	CIE Marks	40
Teaching Hours / Week (L:T:P)	3:0:0	SEE Marks	60
Credits	03	Exam Hours	03

Course Learning Objectives:

- The present course highlights the importance of general safety and its prevention.
- It enables students to understand about mechanical, electrical sand chemical safety.
- The Industrial safety course helps in motivating the students to understand the reason for fire
- Its Controlling of fire by various means are highlighted.
- Importance of chemical safety, labelling of chemicals, hand signals during forklift operations in industrial and aerodromes will help in to understand and apply the techniques in practical field.
- A visit to campus, various labs, workshops, local industries and fire stations helps in analyzing the importance of safety and corrective measures through case studies.

Module-1

Terms used: accident, safety, hazard, safe, safety devices, safety guard, security, precaution, caution, appliance, slip, trip, fall. Ladders and scaffolding. Unsafe acts, reason for accidents, MSDS (material safety data sheet), computer Aided Hazard Analysis, International acts and standards OSHA, WHO. Environment act, control and abatement of environmental pollution-Biomedical waste. Lockout and tag out procedures. Safe material handling and storage. Risk analysis quantification.

Case studies: Student should identify the unsafe acts near their surroundings like housekeeping, lab as well as industrial layouts, road safety, campus layout, safety signs.

Module-2

Introduction, toxicity of products of combustion – vapour clouds – flash fire – jet fires – pool fires – autoignition, sources of ignition. Class A, B, C, D and E fire. Fire triangle, Fire extinguishers, Fire hazard and analysis, prevention of fire. Fire protection and loss prevention, steps after occurrence of fire. notice-first aid for burns, Portable fire extinguishers. Fire detection, fire alarm and firefighting systems. Safety sign boards,

instruction on portable fire extinguishers. Case studies: demonstration of fire extinguishers, visit to local fire fighting stations. Visit to fire accident sites to analyze the cause of fire and its prevention for future.

Module-3

PPE, safety guards, Mechanical hazards, workplace hazards, Forklift hazard control Safety while working with machine tools like lathe, drill press, power and band saws, grinding machines. Safety during welding, forging and pressing. Safety while handling Material, compressed gas cylinders, corrosive substance, waste drum and containers.

Case studies: Visit to machine shop, workshops, foundry lab and local industries to record the practical observation and report the same with relevant figures and comments.

Module-4

Introduction to electrical safety, Indian standards on electrical safety, Electric hazards, effect of electric current on human body, causes of electrical accidents, prevention of electric accidents, PPE used. Protection systems: Fuse, circuit breakers and overload relays – protection against over voltage and under voltage. Electric shock. Primary and secondary electric shocks, AC and DC current shocks. Safety precautions against shocks. Safety precautions in small and residential building installations. Safety procedures in electric plant. Case studies: To visit electrical sub stations, local distribution systems, observe and share the experience and report.

Module-5

Introduction to Chemical safety, Labelling of chemicals, acid hoods. Handling of acids, eye washers and showers. Safety thinking, accident investigation, safety policy of the company, safety, loss prevention and control, check list for LPG installations, safety precautions using CNG, fire prevention and safety audit, confined space entry, risk assessment.

Case studies: To visit chemical laboratory of the college and other chemical industries like LPG , CNG facilities and report.

Course Outcomes: At the end of the course, the student will be able to:

CO1: Understand the basic safety terms and international standards.

- CO2: Identify the hazards and risk analysis around the work environment and industries.
- CO3: Use the safe measures while performing work in and around the work area of the available laboratories. Able to recognize the sign boards and its application
- CO4: Recognise the types of fires extinguishers and to demonstrate the portable extinguishers used for different classes of fires.
- CO5: Report the case studies by sharing experience of the employees working in housekeeping, laboratories like workshops, electrical labs, machine shops, electronics and computer laboratories.

CO6: Recognise the chemical and electrical hazards for its prevention and control.

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.
- There will be two full questions (with a maximum of four sub- questions) from each module.
- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.

SI. No.	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year
Textb	ook/s			
1	Industrial Safety and Management	L M Deshmukh	McGraw Hill Education (India) private Limited	ISBN-13: 978-0-07- 061768-1
2	Fire Prevention Hand Book	Derek, James	Butter Worth's and Company, London	1986
3	Electrical Safety, fire safety and safety management	S.Rao, R K Jain and Saluja	Khanna Publishers	ISBN: 978- 81-7409- 306-6
4	Industrial health and safety management	A.M.Sarma	Himalya publishing house	
5	Chemical process Industrial safety	K S N Raju	McGraw Hill Education (India) private Limited.	ISBN-13: 978-93-329- 0278-7
6	Environmental engineering	Gerard Kiely	McGraw Hill Education (India) private Limited	ISBN-13: 978-0-07- 063429-9
Refere	ence Books			1
1	The Environment Act (Protection) 1986	Commercial Law Publishers (India) Pvt. Ltd. New Delhi.		
2	Water (Prevention and control of pollution) act 1974	Commercial Law publishers (India)		

		Pvt. Ltd., New Delhi.		
•	To visit respective Institution: sto	res, office, housekeep	ing area, laboratories.	
•	To visit local industries, workshop	os, district firefighting	system facility and local electrica	al power
	stations.			

OPEN ELECTIVE B **B. E. MECHANICAL ENGINEERING**

Choice Based Credit System (CBCS) and Outcome Based Education (OBE)

SEMESTER – VII

	OPTIMISATION TECHNIQUES		
Course Code	18ME754	CIE Marks	40
Teaching Hours / Week (L:T:P)	3:0:0	SEE Marks	60
Credits	03	Exam Hours	03

Course Learning Objectives:

- To expose the students to techniques to optimize complex engineering problems.
- To introduce non-linear programming techniques.
- To introduce the Integer programming method.

Module-1

Introduction: Statement of optimisation problem, Design vector, Design constraints, Objective function, Classification of optimisation problems based on :constraints, nature of design variables, nature of the equations involved

Single variable optimisation: Necessary and sufficient conditions, Multivariable optimization with no constraints: Necessary and sufficient conditions, Semi definite case, Saddle point, Multi variable optimization with equality constraints, Solution by direct substitution, Lagrange Multipliers, Interpretation of Lagrange multipliers, Multivariable optimization with inequality constraints: Khun Tucker conditions(concept only).

Module-2

Nonlinear Programming: One-Dimensional Minimization Methods, Introduction, Unimodal Function, Elimination methods: unrestricted search, fixed step size, accelerated step size, Exhaustive search: dichotomous search, interval halving method, Fibonacci method, golden section method, Interpolation methods: Quadratic and cubic interpolation method, direct root method, Newton method, Quasi-Newton method, secant method.

Module-3

Nonlinear Programming: Direct search methods: Classification of unconstrained minimization methods, rate of convergence, scaling of design variables, random search methods, univariate methods, pattern directions, Powell's methods, Simplex method.

Module-4

Nonlinear Programming: Indirect Search (Descent) Methods: Gradient of a function, Steepest decent method, Fletcher Reeves method, Newton's method, Davidson-Fletcher-Powell method.

Module-5

Integer Programming: Introduction, Graphical representation, Gomory's cutting plane method: concept of a cutting plane, Gomory's method for all-integer programming problems, Bala's algorithm for zero–one programming, Branch-and-Bound Method.

Course Outcomes: At the end of the course, the student will be able to:

CO1: Define and use optimization terminology, concepts, and understand how to classify an optimization problem.

CO2: Understand how to classify an optimization problem.

CO3: Apply the mathematical concepts formulate the problem of the systems.

CO4: Analyse the problems for optimal solution using the algorithms.

CO5: Interpret the optimum solution.

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.
- There will be two full questions (with a maximum of four sub- questions) from each module.
- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.
- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.

SI. No.	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year
Textbo	ook/s			
1	Engineering Optimization Theory and Practice	S. S. Rao	John Wiley & Sons	Fourth Edition 2009
2	Optimisation Concepts and Applications in Engineering	A. D. Belegundu, T.R. Chanrupatla,	Cambridge University Press	2011
Refere	nce Books			
1	Engineering Optimization: Methods and Applications	Ravindran, K. M. Ragsdell, and G. V. Reklaitis	Wiley, New York	2nd ed. 2006

	Choice Based Cr	SEMESTER - V	itcome Based Education (OBE)	
		SEIVIESTER - V		
Cour	se Code	18MEL76	CIE Marks	40
Геас	hing Hours /Week (L:T:P)	0:2:2	SEE Marks	60
Cred	its	02	Exam Hours	03
	through CNC simulation soTo educate the students oTo make the students und	oftware by using G-Codes a in the usage of CAM package lerstand the importance of		-
<u></u>	FMS, Robotics, and Hydra			
SI.		Experime	nts	
No.		PART - A		
1		ning using ISO Format G/M rection of syntax and logic	codesfor 2 turning and 2 milling cal errors, and verification of too	• •
		PART - B		
2	3 typical simulations to be CAM. Program generation u	carried out using simulat using software. Optimize sp	on of Turning, Drilling, Milling op ion packages like: CademCAMI pindle power, torque utilization	Lab-Pro, Master , and cycle time
2	3 typical simulations to be CAM. Program generation u Generation and printing of layouts. Cut the part in single	carried out using simulat using software. Optimize sp shop documents like pro e block and auto mode and	ion packages like: CademCAMI	L ab-Pro, Maste , and cycle time pol list, and too een.
2	3 typical simulations to be CAM. Program generation u Generation and printing of layouts. Cut the part in single Post processingof CNC pro-	carried out using simulat using software. Optimize sp shop documents like pro e block and auto mode and	ion packages like: CademCAMI bindle power, torque utilization bcess and cycle time sheets, to measure the virtual part on scro	L ab-Pro, Master , and cycle time pol list, and too een.
2	3 typical simulations to be CAM. Program generation u Generation and printing of layouts. Cut the part in single Post processingof CNC pro MISTUBISHI. (Only for Demo/Viva voce) FMS (Flexible Manufacturin and linear shuttle conveyor carried out on simple compo Robot programming: Using of objects (2 programs). Pneumatics and Hydraulics,	carried out using simulat using software. Optimize sp shop documents like pro- e block and auto mode and ograms for standard CNC <u>PART - C</u> g System): Programming o Interfacing CNC lathe, mil onents. Teach Pendent & Offline p	ion packages like: CademCAMI bindle power, torque utilization bcess and cycle time sheets, to measure the virtual part on scro	Lab-Pro, Master , and cycle time pol list, and too een. SINUMERIC an val system (ASRS and ASRS to b and place, stackin
3	3 typical simulations to be CAM. Program generation of Generation and printing of layouts. Cut the part in single Post processingof CNC pro- MISTUBISHI. (Only for Demo/Viva voce) FMS (Flexible Manufacturin and linear shuttle conveyor carried out on simple compo- Robot programming: Using of objects (2 programs). Pneumatics and Hydraulics, conducted.	carried out using simulat using software. Optimize sp shop documents like pro- e block and auto mode and ograms for standard CNC PART - C g System): Programming o Interfacing CNC lathe, mil onents. Teach Pendent & Offline p Electro-Pneumatics: 3 typ	ion packages like: CademCAMI pindle power, torque utilization poess and cycle time sheets, to measure the virtual part on scru- control systems like FANUC , f Automatic storage and Retriev ling with loading unloading arm programming to perform pick an	Lab-Pro, Master , and cycle time pol list, and too een. SINUMERIC an val system (ASRS and ASRS to b and place, stackin
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	Choice Based Cr	edit System (CBCS) and Outcon	ne Based Education (OBE)			
		SEMESTER - VII DESIGN LAB				
Course Code 18MEL77 CIE Marks 40						
	hing Hours /Week (L:T:P)	0:2:2	SEE Marks	60		
Credi		02	Exam Hours	03		
	se Learning Objectives:	02	Examinedito			
	ratio.	ts of natural frequency, logarith ques of balancing of rotating ma		nd damping		
	 To verify the concept of the concept o	e critical speed of a rotating sh	aft.			
		f stress concentration using Pho				
		ium speed, sensitiveness, powe				
	 To illustrate the principles 	of pressure development in an	on mini or a nyurouynamic jo	burnar bearing.		
SI.		Experiments				
No.						
1	Determination of natural fra	PART - A quency, logarithmic decrement	damning ratio and damning	t coefficient in		
T		rating systems (longitudinal and		g coencient in		
2	Balancing of rotating masses					
2	Determination of critical spe					
4	-	n speed, sensitiveness, power a	nd effort of Porter/Proell /H:	artnol		
7	Governor.	r specu, sensitiveness, power a				
	Governor	PART - B				
5	Determination of Fringe con	stant of Photo-elastic material u	using.			
-	a) Circular disc subjected to					
	b) Pure bending specimen (fo					
6		centration using Photo-elasticity	y for simple components like	plate with a		
	hole under tension or bendir	ng, circular disk with circular ho	le under compression, 2D Cr	ane hook		
7	Determination of Pressure d	istribution in Journal bearing				
8	Determination of Principal S	tresses and strains in a member	r subjected to combined load	ling using Strai		
9	Determination of stresses in	Curved beam using strain gaug	e.			
Cour	se Outcomes: At the end of th	e course, the student will be at	ole to:			
		cy of the free and forced vibrat		systems,		
critic	al					
	speed of shafts.					
CO2:	Carry out balancing of rotatin	g masses.				
	Analyse the governor charact	-				
	, .	eams, plates and hook using pho	oto elastic hench			
	Determination of Pressure dis					
		-	scion and handing toot and at	r		
	•	using strain gauges in compres	ssion and bending test and st	1855		
aistri	ibution					
	in curved beams.					
	luct of Practical Examination:					
2. Bro		b be included for practical exam ctions printed on the cover pag		tly adhered by		

Scheme of Examination: One question from Part A: 40 marks One question from Part B: 40 Marks Viva voce: 20 Marks Total: 100 Marks

B. E. MECHANICAL ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) **SEMESTER - VIII**

	ENERGY ENG	INEERING	
Course Code	18ME81	CIE Marks	40
Teaching Hours /Week (L:T:P)	3:0:0	SEE Marks	60
Credits	03	Exam Hours	03

Course Learning Objectives:

- Understand energy scenario, energy sources and their utilization
- Learn about energy conversion methods
- Study the principles of renewable energy conversion systems.

Module-1

STEAM GENERATORS Coal and ash handling, Generation of steam using forced circulation, high and supercritical pressures, LaMount, Benson, Velox, Loeffer, Schmidt steam generators, Cooling towers and Ponds, Accessories such as Superheaters, De-superheater, Economizers, Air preheaters.

Module-2

Solar Energy: Introduction, Solar radiation at the earth's surface, Solar radiation measurements, Flat plate collectors, Focussing collectors, Solar pond, Solar electric power generation-Solar photovoltaics.

Biomass Energy: Photosynthesis, photosynthetic oxygen production, energy plantation. Bio Chemical Route: Biogas production from organic wastes by anaerobic fermentation, Bio gas plants-KVIC, Janta, Deenbhandu models, factors affecting bio gas generation. Thermal gasification of biomass, updraft and downdraft Module-3

Geothermal Energy: Forms of geothermal energy, Dry steam, wet steam, hot dry rock and magmatic chamber systems.

Tidal Energy: Tidal power, Site selection, Single basin and double basin systems, Advantages and disadvantages of tidal energy.

Wind Energy: Wind energy-Advantages and limitations, wind velocity and wind power, Basic components of wind energy conversion systems, horizontal and vertical axis wind mills, coefficient of performance of a wind mill rotor, Applications of wind energy.

Module-4

Hydroelectric plants: Advantages & disadvantages of water power, Hydrographs and flow duration curvesnumericals, Storage and pondage, General layout of hydel power plants- components such as Penstock, surge tanks, spill way and draft tube and their applications, pumped storage plants, Detailed classification of hydroelectric plants, water hammer.

Ocean Thermal Energy: Ocean thermal energy conversion, Principle and working of Rankine cycle, Problems associated with OTEC.

Module-5

NUCLEAR ENERGY Principles of release of nuclear energy-Fusion and fission reactions. Nuclear fuels used in the reactors, Chain reaction, Moderation, breeding, Multiplication and thermal utilization factors. General components of a nuclear reactor and materials, Brief description-Pressurized water reactor, Boiling water reactor, Sodium graphite reactor, Fast Breeder reactor, Homogeneous graphite reactor and gas cooled reactor, Radiation hazards, Shielding, Nuclear waste, Radioactive waste disposal.

Course Outcomes: At the end of the course the student will be able to:

CO1: Understand the construction and working of steam generators and their accessories.

CO2: Identify renewable energy sources and their utilization.

CO3: Understand principles of energy conversion from alternate sources including wind, geothermal, ocean, biomass, nuclear, hydel and tidal.

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.
- There will be two full questions (with a maximum of four sub- questions) from each module.
- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.

SI No	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year
Textbo	ook/s	•		·
1	Power Plant Engineering	P. K. Nag	Tata McGraw Hill Education Private Limited, New Delhi	Third Edition, 2012.
2	Power Plant Engineering	Arora and Domkundwar	Dhanpat Rai & Co. (P) Ltd.	Sixth Edition, 2012.
3	Non-conventional Sources of Energy	G.D.Rai	Khanna Publishers, New Delhi	Fifth Edition, 2015.
4	Non-conventional energy resources	B H Khan	McGraw Hill Education	3rd Edition
Refere	ence Books			
1	Power Plant Engineering	R. K. Rajput	Laxmi publication New Delhi	
2	Principles of Energy conversion	A. W. Culp Jr	McGraw Hill	1996
3	Power Plant Technology	M.M. EL-Wakil	McGraw Hill International	1994
4	Solar Energy: principles of Thermal Collection and Storage	S.P. Sukhatme	Tata McGraw-Hill	1984

B. E. MECHANICAL ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER - VIII Professional Elective-4

		013	
Course Code	18ME821	CIE Marks	40
Teaching Hours /Week (L:T:P)	3:0:0	SEE Marks	60
Credits	03	Exam Hours	03

Course Learning Objectives:

- To understand fundamentals of the CNC technology.
- To get exposed to constructional features of CNC machine tools.
- To know the concepts of CNC machine tool drives and feedback systems.
- To understand the programming methods in CNC machines.
- To understand the cutting tools used, and work holding devices on CNC machine tools.

Module-1

INTRODUCTION TO CNC MACHINE TOOLS: Evolution of CNC Technology, principles, features, advantages, applications, CNC and DNC concept, classification of CNC Machines – turning centre, machining centre, grinding machine, EDM, types of control systems, CNC controllers, characteristics, interpolators– Computer Aided Inspection.

Module-2

STRUCTURE OF CNC MACHINE TOOL: CNC Machine building, structural details, configuration and design, guide ways – Friction, Anti friction and other types of guide ways, elements used to convert the rotary motion to a linear motion – Screw and nut, recirculating ball screw, planetary roller screw, recirculating roller screw, rack and pinion, spindle assembly, torque transmission elements – gears, timing belts, flexible couplings, Bearings.

Module-3

DRIVES AND CONTROLS: Spindle drives – DC shunt motor, 3 phase AC induction motor, feed drives –stepper motor, servo principle, DC and AC servomotors, Open loop and closed loop control, Axis measuring system – synchro, synchro-resolver, gratings, moiré fringe gratings, encoders, inductosysn, laser interferometer.

Module-4

CNC PROGRAMMING: Coordinate system, structure of a part program, G & M Codes, tool length compensation, cutter radius and tool nose radius compensation, do loops, subroutines, canned cycles, mirror image, parametric programming, machining cycles, manual part programming for machining centre and turning centre.

Computer Aided CNC Part Programming: Need for computer aided part programming, Tools for computer aided part programming, APT, CAD/CAM based part programming for well-known controllers such as Fanuc, Heidenhain, Sinumerik etc., and generation of CNC codes from CAM packages.

Module-5

TOOLING AND WORK HOLDING DEVICES: Introduction to cutting tool materials – Carbides, Ceramics, CBN, PCD–inserts classification, qualified, semi qualified and pre-set tooling, tooling system for Machining centre and Turning centre, work holding devices for rotating and fixed work parts, modular fixtures, economics of CNC, maintenance of CNC machines.

Course Outcomes: At the end of the course the student will be able to:

- CO1: Understand evolution, classification and principles of CNC machine tools.
- CO2: Learn constructional details of CNC machine tools, selection of standard components used for CNC machine tools for accuracy and productivity enhancement.
- CO3: Select drives and positional transducers for CNC machine tools.
- CO4: Apply CNC programing concepts of for two axis turning centers and three axis vertical milling centers to generate programs different components.

CO5: Generate CNC programs for popular CNC controllers.

CO6: Analyse and select tooling and work holding devices for different components to be machined on CNC machine tools.

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.
- There will be two full questions (with a maximum of four sub- questions) from each module.
- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.

SI No	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year
Textbo	ok/s			
1	Mechatronics	НМТ	Tata McGraw-Hill Publishing Company Limited, New Delhi	2005
2	Computer Control of Manufacturing systems	Koren Y	McGraw Hill	1986
3	Computer Numerical Control Machines	Radhakrishnan P	New Central Book Agency	2002
Referen	nce Books			
1	CNC Machining Hand Book	James Madison	Industrial Press Inc	1996
2	Programming of CNC Machines	Ken Evans, John Polywka& Stanley Gabrel	Industrial Press Inc, New York	Second Edition2002
3	CNC Programming Hand book	Peter Smid	Industrial Press Inc	2000
4	CAD/CAM	Rao P.N.	Tata McGraw-Hill Publishing Company Limited	2002
5	Computer Numerical Control	Warren S. Seames	Thomson Delmar	Fourth Edition 2002

B. E. MECHANICAL ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER - VIII Professional Elective-4 TRIBOLOGY

111201001			
Course Code	18ME822	CIE Marks	40
Teaching Hours /Week (L:T:P)	3:0:0	SEE Marks	60
Credits	03	Exam Hours	03

Course Learning Objectives:

- To educate the students on the importance of friction, the related theories/laws of sliding and rolling friction and the effect of viscosity of lubricants.
- To expose the students to the consequences of wear, wear mechanisms, wear theories and analysis of wear problems.
- To make the students understand the principles of lubrication, lubrication regimes, theories of hydrodynamic and the advanced lubrication techniques.
- To expose the students to the factors influencing the selection of bearing materials for different sliding applications.
- To introduce the concepts of surface engineering and its importance in tribology.

Module-1

Introduction to tribology: Historical background, practical importance, and subsequent use in the field. **Lubricants**: Types and specific field of applications. Properties of lubricants, viscosity, its measurement, effect of temperature and pressure on viscosity, lubrication types, standard grades of lubricants, and selection of lubricants.

Module-2

Friction: Origin, friction theories, measurement methods, friction of metals and non-metals. **Wear:** Classification and mechanisms of wear, delamination theory, debris analysis, testing methods and standards. Related case studies.

Module-3

Hydrodynamic journal bearings: Friction forces and power loss in a lightly loaded journal bearing, Petroff's equation, mechanism of pressure development in an oil film, and Reynold's equation in 2D.

Introduction to idealized journal bearing, load carrying capacity, condition for equilibrium, Sommerfeld's number and it's significance; partial bearings, end leakages in journal bearing, numerical examples.

Module-4

Plane slider bearings with fixed/pivoted shoe: Pressure distribution, Load carrying capacity, coefficient of friction, frictional resistance in a fixed/pivoted shoe bearing, center of pressure, numerical examples.

Hydrostatic Lubrication: Introduction to hydrostatic lubrication, hydrostatic step bearings, load carrying capacity and oil flow through the hydrostatic step bearing, numerical examples. Introduction to Hydrostatic journal bearings.

Module-5

Bearing Materials: Commonly used bearings materials, and properties of typical bearing materials. Advantages and disadvantages of bearing materials.

Introduction to Surface engineering: Concept and scope of surface engineering.

Surface modification – transformation hardening, surface melting, thermo chemical processes.

Surface Coating – plating, fusion processes, vapor phase processes. Selection of coating for wear and corrosion resistance.

Course Outcomes: At the end of the course, the student will be able to:

CO1: Understand the fundamentals of tribology and associated parameters.

CO2: Apply concepts of tribology for the performance analysis and design of components experiencing relative

motion.

CO3: Analyse the requirements and design hydrodynamic journal and plane slider bearings for a given application.

CO4: Select proper bearing materials and lubricants for a given tribological application.

CO5: Apply the principles of surface engineering for different applications of tribology.

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.
- There will be two full questions (with a maximum of four sub- questions) from each module.
- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.

SI No	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year
Textbo	ok/s	1		
1	Introduction to Tribology	B. Bhushan	John Wiley & Sons, Inc., New York	2002
2	Engineering Tribology	Prasanta Sahoo	PHI Learning Private Ltd, New Delhi	2011
3	Engineering Tribology	J. A. Williams	Oxford Univ. Press	2005
Referer	nce Books	1		
1	Introduction to Tribology in bearings	B. C. Majumdar	Wheeler Publishing	
2	Engineering Tribology	G. W. Stachowiak and A. W. Batchelor	Butterworth-Heinemann	1992
3	Friction and Wear of Materials	Ernest Rabinowicz	John Wiley &Sons	1995
4	Basic Lubrication Theory	A. Cameron	Ellis Hardwoods Ltd., UK	
5	Handbook of tribology: materials, coatings and surface treatments	B.Bhushan, B.K. Gupta	McGraw-Hill	1997

Choice Based Crec		GINEERING		
		Itcome Based Education (OBE)	
SEMESTER - VIII Professional Elective-4				
NON	-DESTRUCTIVE TESTING			
Course Code	18ME823	CIE Marks	40	
Teaching Hours /Week (L:T:P)	3:0:0	SEE Marks	60	
Credits	03	Exam Hours	03	
	ethods such as Visual, Per phy, Eddy Current. priate NDT methods. mitations of NDT method			
OVERVIEW OF NDT: NDT Versus Me the detection of manufacturing defect Various physical characteristics of ma aided. Module-2	cts as well as material cha	aracterisation. Relative merits	and limitations,	
and evaluation of test indications Pr			ods, Interpretation	
Module-3 THERMOGRAPHY AND EDDY CURR inspection methods, Techniques for a infrared detectors, Instrumentations currents, Properties of eddy curren arrangement, Applications, advantag	ENT TESTING (ET): Ther applying liquid crystals, A s and methods, applica hts, Eddy current sensir	dvantages and limitation – inf tions. Eddy Current Testing-G g elements, Probes, Instrum	gnetism. t and non -contact rared radiation and Generation of eddy	
Module-3 THERMOGRAPHY AND EDDY CURR inspection methods, Techniques for a infrared detectors, Instrumentations currents, Properties of eddy current	ENT TESTING (ET): Ther applying liquid crystals, A s and methods, applica hts, Eddy current sensir	mography- Principles, Contact dvantages and limitation – inf tions. Eddy Current Testing-G g elements, Probes, Instrum	gnetism. t and non -contact rared radiation and Generation of eddy	
Module-3 THERMOGRAPHY AND EDDY CURR inspection methods, Techniques for a infrared detectors, Instrumentations currents, Properties of eddy curren arrangement, Applications, advantag Module-4 ULTRASONIC TESTING (UT) AND ACC Ultrasonic Testing-Principle, Transduc beam, instrumentation, data represe Diffraction. Acoustic Emission Techni	ENT TESTING (ET): Ther applying liquid crystals, A s and methods, applica- nts, Eddy current sensir es, Limitations, Interpret DUSTIC EMISSION (AE): cers, transmission and pu- ntation, A/Scan, B-scan,	mography- Principles, Contact dvantages and limitation – inf tions. Eddy Current Testing-G g elements, Probes, Instrum ation/Evaluation. Ilse-echo method, straight bea C-scan. Phased Array Ultrasou	gnetism. t and non -contact rared radiation and Generation of eddy entation, Types of am and angle	
Module-3 THERMOGRAPHY AND EDDY CURR inspection methods, Techniques for a infrared detectors, Instrumentations currents, Properties of eddy curren arrangement, Applications, advantag Module-4 ULTRASONIC TESTING (UT) AND ACC Ultrasonic Testing-Principle, Transdue beam, instrumentation, data represe	ENT TESTING (ET): Ther applying liquid crystals, A s and methods, applica- nts, Eddy current sensir es, Limitations, Interpret DUSTIC EMISSION (AE): cers, transmission and pu- ntation, A/Scan, B-scan, que –Principle, AE param action of X-Ray with mat metric factors, Inverse s stic curves, Penetramet	mography- Principles, Contact dvantages and limitation – inf tions. Eddy Current Testing-G g elements, Probes, Instrum ation/Evaluation. Ilse-echo method, straight bea C-scan. Phased Array Ultrasou leters, Applications. ter, imaging, film and film less quare, law, characteristics of ers, Exposure charts, Radiogr	gnetism. t and non -contact rared radiation and Generation of eddy entation, Types of am and angle nd, Time of Flight s techniques, types films – graininess,	
Module-3 THERMOGRAPHY AND EDDY CURR inspection methods, Techniques for a infrared detectors, Instrumentations currents, Properties of eddy curren arrangement, Applications, advantag Module-4 ULTRASONIC TESTING (UT) AND ACC Ultrasonic Testing-Principle, Transdue beam, instrumentation, data represe Diffraction. Acoustic Emission Techni Module-5 RADIOGRAPHY (RT): Principle, intera and use of filters and screens, geor density, speed, contrast, characteria	ENT TESTING (ET): Ther applying liquid crystals, A s and methods, applica- nts, Eddy current sensir es, Limitations, Interpret DUSTIC EMISSION (AE): cers, transmission and pu- ntation, A/Scan, B-scan, que –Principle, AE param ction of X-Ray with mat metric factors, Inverse s stic curves, Penetramet oputed Radiography, Com course the student will b ive testing methods. ys by visual inspection ma- uctive tests like: Liquid per diography, Leak Test, Edd	mography- Principles, Contact dvantages and limitation – inf tions. Eddy Current Testing-G g elements, Probes, Instrum ation/Evaluation. ulse-echo method, straight bea C-scan. Phased Array Ultrasou teters, Applications. ter, imaging, film and film less quare, law, characteristics of ers, Exposure charts, Radiogr puted Tomography. e able to: ethod. enetrant test, Magnetic particle	gnetism. t and non -contact rared radiation and Generation of eddy entation, Types of am and angle nd, Time of Flight s techniques, types films – graininess, raphic equivalence.	

CO6: Document the testing and evaluation of the results.

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.
- There will be two full questions (with a maximum of four sub- questions) from each module.
- Each full question will have sub- question covering all the topics under a module.

SI No	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year
Textbo	ok/s		•	
1	Practical Non-Destructive Testing	Baldev Raj, T.Jayakumar, M.Thavasimuthu	Narosa Publishing House	2009
2	Non-Destructive Testing Techniques	Ravi Prakash	New Age International Publishers	1st revised edition2010
Refere	nce Books			
1	ASM Metals Handbook,"Non- Destructive Evaluation and Quality Control", Volume-17	American Society of Metals,	Metals Park, Ohio, USA,	2000
2	Introduction to Non- destructive testing: a training guide	Paul E Mix,	Wiley	2nd Edition New Jersey, 2005
3	Handbook of Nondestructive evaluation	Charles, J. Hellier	McGraw Hill, New York	2001
2, Liqui	American Society for Non Destruct d Penetrant Testing, Vol. 3, Infrare magnetic Testing, Vol. 6, Acoustic	ed and Thermal Testing Vol	l. 4, Radiographic Testing, \	-

B.E, VIII Semester, Mechanical Engineering Choice Based Credit System (CBCS) and Outcome Based Education (OBE) (Effective from the academic year 2018-19)

Professional Elective-IV

AUTOMOBILE ENGINEERING

Course Code	18ME824	CIE Marks	40
Teaching Hours /Week (L:T:P)	3:0:0	SEE Marks	60
Credits	03	Exam Hours	03

Course Learning Objectives:

- The layout and arrangement of principal parts of an automobile
- The working of transmission and brake systems
- The operation and working of steering and suspension systems
- To know the Injection system and its advancements
- To know the automobile emissions and its effects on environment

Module - 1

ENGINE COMPONENTS AND IT'S PRINCIPLE PARTS: Spark Ignition (SI) & Compression Ignition (CI) engines, cylinder – arrangements and their relatives merits, Liners, Piston, connecting rod, crankshaft, valves, valve actuating mechanisms, valve and port timing diagrams, Types of combustion chambers for S.I.Engine and C.I.Engines, methods of a Swirl generation, choice of materials for different engine components, engine positioning. Concept of HCCI engines, hybrid engines, twin spark engine, electric car. **COOLING AND LUBRICATION**: cooling requirements, types of cooling- thermo siphon system, forced circulation water cooling system, water pump, Radiator, thermostat valves. Significance of lubrication, splash and forced feed system.

Module - 2

TRANSMISSION SYSTEMS: Clutch-types and construction, gear boxes- manual and automatic, gear shift mechanisms, over drive, transfer box, fluid flywheel, torque converter, propeller shaft, slip joints, universal joints, Differential and rear axle, Hotchkiss Drive and Torque Tube Drive. BRAKES: Types of brakes, mechanical compressed air, vacuum and hydraulic braking systems, construction and working of master and wheel cylinder, brake shoe arrangements, Disk brakes, drum brakes, Antilock –Braking systems, purpose and operation of antilock-braking system, ABS Hydraulic Unit, Rear-wheel antilock & Numerical

Module - 3

STEERING AND SUSPENSION SYSTEMS: Steering geometry and types of steering gear box-Power Steering, Types of Front Axle, Suspension, Torsion bar suspension systems, leaf spring, coil spring, independent suspension for front wheel and rear wheel, Air suspension system. IGNITION SYSTEM: Battery Ignition system, Magneto Ignition system, electronic Ignition system

Module - 4

SUPERCHARGERS AND TURBOCHARGERS: Naturally aspirated engines, Forced Induction, Types of superchargers, Turbocharger construction and operation, Intercooler, Turbocharger lag.

FUELS, FUEL SUPPLY SYSTEMS FOR SI AND CI ENGINES: Conventional fuels, alternative fuels,

normal and abnormal combustion, cetane and octane numbers, Fuel mixture requirements for SI engines, types of carburetors, C.D.& C.C. carburetors, multi point and single point fuel injection systems, fuel transfer pumps, Fuel filters, fuel injection pumps and injectors. Electronic Injection system, Common Rail Direct Injection System

Module - 5

AUTOMOTIVE EMISSION CONTROL SYSTEMS: Different air pollutants, formation of photochemical smog and causes. Automotive emission controls, controlling crankcase emissions, controlling evaporative emissions, Cleaning the exhaust gas, Controlling the air-fuel mixture, Controlling the combustion process, Exhaust gas recirculation, Treating the exhaust gas, Air-injection system, Air-aspirator system, Catalytic converter.

EMISSION STANDARDS: Euro I, II, III and IV norms, Bharat Stage II, III, IV norms. Motor Vehicle Act

Course Outcomes:

- To identify the different parts of an automobile and it's working
- To understand the working of transmission and braking systems
- To comprehend the working of steering and suspension systems
- To learn various types of fuels and injection systems

•To know the cause of automobile emissions, its effects on environment and methods to reduce the emissions.

TEXT BOOKS:

- 1. Automobile engineering, Kirpal Singh, Vol I and II (12th Edition) Standard Publishers 2011
- 2. Automotive Mechanics, S. Srinivasan, (2nd Edition) Tata McGraw Hill 2003.

REFERENCE BOOKS

- 1. Automotive mechanics, William H Crouse & Donald L Anglin (10th Edition) Tata McGraw Hill Publishing Company Ltd., 2007.
- 2. Automotive mechanics: Principles and Practices, Joseph Heitner, D Van Nostrand Company, Inc
- 3. Fundamentals of Automobile Engineering, K.K.Ramalingam, Scitech Publications (India) Pvt. Ltd.
- 4. Automobile Engineering, R. B. Gupta, SatyaPrakashan, (4th Edition) 1984.

B. E. MECHANICAL ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER - VIII Professional Elective-4 TOOL DESIGN

Course Code	18ME825	CIE Marks	40
Teaching Hours /Week (L:T:P)	3:0:0	SEE Marks	60
Credits	03	Exam Hours	03

Course Learning Objectives:

- To develop capability to design and select single point and multipoint cutting tools for various machining operations.
- Exposure to variety of locating and clamping methods available.
- To enable the students to design jigs and fixtures for simple components.
- To expose the students to the design/selection procedure of press tools and die casting dies.

Module-1

Introduction to tool design: Tooling, requirements of a tool designer, general tool design procedure, tool engineering functions and its importance to enhance productivity and quality.

Review of cutting tool materials. Tool angles and signature, Carbide inserts grades - ISO designation and applications, tool holders for turning-ISO designation. Solid type tool, brazed tip tool, throwaway indexable insert types, coated carbides and chip breakers.

Design of single point cutting tools: Design of shank dimensions using strength and rigidity considerations for rectangular, square and round cross section and selection of tool geometry.

Module-2

Design of Multi Point Cutting Tools: Types of drills, Drill bit design - elements like back taper, web thickness, land width, margin, flute length and cross section and selection of tool geometry. Re-sharpening of drill bit. Tool holders for milling, different tapers used for mounting tool holders in milling, ISO designation. Tool mounting systems.

Design of milling cutters: Design of elements like number of teeth and height, circular pitch, body thickness, chamfer width, fillet radius and selection of tool geometry. Profile sharpened and form relieved milling cutters. Re-sharpening of side and face milling cutter and end mill.

Module-3

Jigs and Fixtures: Functions and differences between jigs and fixtures, advantages in mass production, design principles, economics of jigs and fixtures.

Location: 3-2-1 Principle of location, different types of locating elements.

Clamping: Principles of clamping, types of clamping devices, and power clamping.

Drill bushes;

Drill jigs: Different types, exercises of designing jigs for simple components.

Fixture Design: Turning fixtures, milling fixtures, grinding fixtures, fixturing for CNC machining centers, and modular fixtures. Design exercises on fixtures for turning and milling for simple components

Module-4

Press tools: Classification and working of power presses. Concept and calculations of press tonnage and shut height of a press, components of a simple die, press tool operation, die accessories, shearing action in punch & die, clearance, shear on punch and die, Centre of pressure, and strip layout.

Simple, progressive, compound, combination and inverted dies. Design problems on blanking and piercing dies for simple components.

Bending dies – Introduction, bend allowance, spring back, edge bending die design.

Module-5

Drawing dies – Single action, double action and triple action dies, factors affecting drawing and drawing die design. Design of drawing dies for simple components.

Die casting: Die casting alloys, terminology- core, cavity, sprue, slug, fixed and movable cores, finger cams, draft, ejector pins and plates, gate, goose nozzle, over-flow, platten, plunger, runner, vent, water-line etc. Types of Dies: Single cavity, multi cavity dies, combination dies, unit dies, advantages and disadvantages of types of dies; finishing, trimming and inspection of die casting components, safety, and modern trends in die casting dies.

Assignment:

Course work includes a **ToolDesign project**. Tool design project should enable the students to design a tooling like Jig or a fixture for a simple component, fixture for a simple component on CNC machining centers, design of a simple blanking and piercing die, progressive die, drawing die etc. Any one of these exercises should be given as an assignment. A group of students (maximum number in a group should be 4) should submit assembly drawing and part drawings, completely dimensioned, indicating the necessary manufacturing tolerances, surface finish symbols and geometric tolerances wherever necessary. Tool design project must be completed using appropriate solid modeling software. Computer generated drawings must be submitted. Design calculations must be hand written and should be included in the report. Tool design project should be given due credit in internal assessment.

Course Outcomes: At the end of the course, the student will be able to:

CO1: Select appropriate cutting tools required for producing a component.

CO2: Understand and interpret cutting tool and tool holder designation systems.

CO3: Select suitable locating and clamping devices for a given component for various operations.

CO4: Analyze and design a jig/fixture for a given simple component.

CO5: Understand various press tools and press tool operations.

CO6: Classify and explain various die casting and injection moulding dies.

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.
- There will be two full questions (with a maximum of four sub- questions) from each module.
- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.

SI No	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year
Textboo	ok/s			
1	Tool Design	Cyril Donaldson,	Mc Graw Hill	5 th edition, 2017
		George H. Lecain, V.C.Goold,	Education	
2	Manufacturing technology	P.N.Rao,	Mc Graw Hill	4 th edition, 2013
			Education	
Referen	ce Books			
1	Jigs and Fixtures	P.H.Joshi	Mc Graw Hill	3 rd edition, 2010
			Education	
2	Fundamentals of Tool Design	John.G. Nee, William	Society of	2010
		Dufraine, John W.	Manufacturing	
		Evans, Mark Hill	Engineers	
3	Fundamentals of Tool Design	Frank W.Wilson	PHI publications	
4	An introduction to Jig and Tool design	Kempester M.H.A	VIVA Books Pvt.Ltd.	2004
5	Metal cutting and Tool Design	RanganathB.J	Vikas publishing house	

Updated on 16.04.2020/28092020

6	Metal cutting theory and practice	V. Arshinov& G. Alekseev	MIR publishers, Moscow	
7	Design and production of metal cutting tools	Rodin	Beekman publishers	
8	Production Technology	HMT	TataMc Graw Hill	2013.

B. E. MECHANICAL ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER - VIII								
Professional Elective-4								
FRACTURE MECHANICS								
Course Code	18ME826	CIE Marks	40					
Teaching Hours /Week (L:T:P)	3:0:0	SEE Marks	60					
Credits	03	Exam Hours	03					
Course Learning Objectives:								
 To expose the students to t 	he fundamentals of mechanic	cs of fracture of materials.						
 The students will learn abo 	ut stress / strain and deforma	tion fields near a crack tip	, fracture					
characterizing parameters	like stress intensity factor and	J integral and kinetics of f	atigue crack					
growth.								
• To expose the students to f	undamentals of linear elastic	fracture mechanics, nonli	near (Elastic-					
Plastic) fracture mechanics	and fatigue crack growth.		-					
•	nethods for determining the f	fracture toughness (for ex	ample ASTM					
standard procedure for JIC	-							
•	failure of structures by fatigu	o crock growth						
To learn the mechanism of Module-1	Tallure of structures by Taligu	e crack growth.						
problems. The Airy stress function. Module-2 Plasticity effects: Theory of Plastic of the plastic zone for plane stres. Determination of Stress intensity stress intensity factors. Experimen requirements, etc.	deformation, Irwin plastic zon s and plane strain cases. The factors and plane strain frac	ne correction. Dugdale's a plate thickness effect, n cture toughness: Introduc	pproach. The shape umerical problems tion, estimation of					
Module-3								
The energy release rate, Criteria modulus. Stability. Elastic plastic fracture mechanics:	Fracture beyond general yie	ld. The Crack-tip opening	displacement. The					
Use of CTOD criteria. Experimental	determination of CTOD. Para	inclus anceling the child	al CTOD.					
•	determination of CTOD. Para	inclus anceang the child	al CTOD.					
Module-4 J integral: Use of J integral. Limi parameters affecting J integral.	itation of J integral. Experir	nental determination of	J integral and the					
Module-4 J integral: Use of J integral. Limi parameters affecting J integral. Dynamics and crack arrest: Crack	itation of J integral. Experir speed and kinetic energy.	nental determination of Dynamic stress intensity	J integral and the and elastic energy					
Module-4 J integral: Use of J integral. Limi parameters affecting J integral. Dynamics and crack arrest: Crack release rate. Crack branching. Princ	itation of J integral. Experir speed and kinetic energy.	nental determination of Dynamic stress intensity	J integral and the and elastic energy					
Module-4 J integral: Use of J integral. Limi	itation of J integral. Experin speed and kinetic energy. iples of crack arrest. Crack an	nental determination of Dynamic stress intensity rest in practice. Dynamic f	J integral and the and elastic energy racture toughness.					

Course Outcomes: At the end of the course the student will be able to:

- CO1: Analyse the effects of crack like defects on the performance of Aerospace, Civil, and Mechanical Engineering structures.
- CO2: Apply the concepts of fracture mechanics to select appropriate materials for engineering structures to insure damage tolerance.
- CO3: Understand mechanics of crack tip fields and appropriate fracture characterizing parameters like stress intensity factor and J integral or nonlinear energy release rate and how to compute them using various methods.
- CO4: Apply the concepts of fracture mechanics to determine critical crack sizes and fatigue crack propagation rates in engineering structures leading to life estimation.

CO5: Understand the status of academic research in field of fracture mechanics.

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.
- There will be two full questions (with a maximum of four sub- questions) from each module.
- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.

SI No	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year
Textbo	ok/s			
1	Elements of fracture mechanics	Prasanth Kumar	Wheeter publication	1999
2	Fracture Mechanics: Fundamentals and Applications	Anderson	CRC press	3rd Ed., 2005
Referer	nce Books			1
1	Introduction to fracture mechanics	Karen Hellan	McGraw Hill	2nd Edition
2	Engineering fracture mechanics	S.A. Meguid	Elsevier Applied Science	1989
3	Fracture of Engineering Brittle Materials	Jayatilaka	Applied Science Publishers	1979
4	Fracture and Fatigue Control in Structures	Rolfe and Barsom	Prentice Hall	1977
5	Engineering Fracture Mechanics	Broek	MartinusNijhoff publishers	1982
6	Advanced Fracture Mechanics	M.F.Kanninen and C.H.Popelar	Oxford press	1985